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Rexroth IndraLogic VPP 21
System Description

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Edition 01

Operating and Programming Guide

Title	Rexroth IndraLogic VPP 21
	System Description
Type of Documentation	Operating and Programming Guide
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Purpose of Documentation	This documentation provides an overview of the components belonging to the PLC system IndraLogic VPP 21 and describes their projecting and programming.

Record of Revisions

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Note   This document has been printed on chlorine-free bleached paper.

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1   System Overview

1.1   Components

Hardware   The PLC system IndraLogic VPP 21 is based on the operator terminal IndraControl VPP 21. It is composed of the following components:

- IndraControl VPP 21 (hardware)

- IndraLogic VPP 21 firmware, including real time operating system VxWorks and VxWinRT.

The IndraControl VPP 21-devices are operator terminals using the operating system Windows XP. As universal hardware platform for visualization applications they can be used in combination with the IndraLogic VPP 21 firmware as soft control also for PLC applications.

Software   The software "IndraWorks Logic" serves to commission and project the IndraLogic VPP 21.
It consists of the following components:

- **IndraWorks:** Project planning, configuration

- **IndraLogic:** PLC programming

- **IndraWorks HMI:** Visualization and user interface as well as diagnostic functions (ProVi)

- **IndraWorks WinStudio:** Engineering tool to create user screens on the IndraControl VPP 21, see below.

- **IndraLogic VPP 21 TSP:** Target files (**T**arget **S**upport **P**ackage) are installed required to edit the IndraLogic VPP 21 with IndraWorks and IndraLogic.

- **Target Manager:** Management of TSP files, e. g., for service updates of control functions.

- **SoftPanel:** Indicating   and   operating   software   on   the IndraLogic VPP 21, description in this documentation.

All components are automatically installed or are pre-installed components on the IndraLogic VPP 21.

Additionally, WinStudio must be installed. The installation file is in the subdirectory "WinStudio" on the installation CD.

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1.2   Related Documentations

No.	Title	Identification
/1/	Rexroth IndraControl VPP 21.1 Project Planning Manual	DOK-SUPPL*-VPP*21.1***-PR..-EN-P
/2/	PLC Programming with Rexroth IndraLogic 1.2; Operating and Programming Guide	DOK-CONTRL-IL**PRO*V02-AW..-EN-P
/3/	Rexroth Inline PROFIBUS DP; Application Manual	DOK-CONTRL-R-IL*PBSSYS-AW..-EN-P
/4/	Rexroth Inline PROFIBUS DP Terminal and Module Supply; Functional Description	DOK-CONTRL-R-IL*PB*-BK-FK..-EN-P
/5/	Rexroth IndraWorks; Operating and Programming Guide	In preparation. Preliminary, in IndraWorks the following Online help files can be called via the help contents under "Working with IndraWorks": - IndraLogic: PLC projecting in IndraWorks - I/O configuration: I/O configuration in IndraWorks - HMI: IndraWorks HMI - IndraWork diagnosis (ProVi)
/6/	Rexroth WinStudio; Overall View	DOK-CONTRL-WIS*PC**V06-KB..-EN-P
/7/	Rexroth IndraLogic; Field bus drive according to PLCOpen, Operating and Programming Guide	In preparation. Preliminary documentation is available.

Fig. 1-1:   Related documentations

2   Important Directions for Use

2.1   Appropriate Use

Introduction

Rexroth products represent state-of-the-art developments and manufacturing. They are tested prior to delivery to ensure operating safety and reliability.

The products may only be used in the manner that is defined as appropriate. If they are used in an inappropriate manner, then situations can develop that may lead to property damage or injury to personnel.

Note: Bosch Rexroth, as manufacturer, is not liable for any damages resulting from inappropriate use. In such cases, the guarantee and the right to payment of damages resulting from inappropriate use are forfeited. The user alone carries all responsibility of the risks.

Before using Rexroth products, make sure that all the pre-requisites for appropriate use of the products are satisfied:

• Personnel that in any way, shape or form uses our products must first read and understand the relevant safety instructions and be familiar with appropriate use.

• If the product takes the form of hardware, then they must remain in their original state, in other words, no structural changes are permitted. It is not permitted to decompile software products or alter source codes.

• Do not mount damaged or faulty products or use them in operation.

• Make sure that the products have been installed in the manner described in the relevant documentation.

Areas of Use and Application

The operator terminals IndraControl VPP 21 are PC-based machine operator terminals, that can also perform control functionalities.

Note: The operator terminals IndraControl VPP 21 may only be used with the accessories and parts specified in document /1/ (see "Related Documentation"). If a component has not been specifically named, then it may not be either mounted or connected. The same applies to cables and lines.

Operation is only permitted in the specified configurations and combinations of components using the software and firmware as specified in the relevant function descriptions.

In case of non-observance the warranty claim expires automatically.

The PLC system IndraLogic VPP 21 has been developed for use in control tasks.

Typical applications of the IndraLogic VPP 21 are:

- Handling and assembly systems,
- Packaging and foodstuff machine,
- Printing and paper processing machines
- Machine tools.

The IndraLogic VPP 21 may only be operated under the assembly, installation and ambient conditions (temperature, system of protection, humidity, EMC requirements, etc.) as described in document /1/ and in the position specified.

In residential areas as well as in business and commercial areas Class A devices may be used with the following note:

Note: This is a Class A device. In a residential area, this device may cause radio interferences. In such a case, the user may be required to introduce suitable countermeasures at his own cost.

2.2 Inappropriate Use

Using the operator terminals IndraControl VPP 21 outside of the above-referenced areas of application or under operating conditions other than described in the document and the technical data specified is defined as "inappropriate use".

The operator terminals IndraControl VPP 21 may not be used, if

- they are subject to operating conditions, that do not meet the above specified ambient conditions. This includes, for example, operation under water, in the case of extreme temperature fluctuations or extremely high maximum temperatures, or if
- Bosch Rexroth has not specifically released them for that intended purpose. Please note the specifications outlined in the general Safety Guidelines!

3   Safety Instructions for Electric Drives and Controls

3.1   Introduction

Read these instructions before the initial startup of the equipment in order to eliminate the risk of bodily harm or material damage. Follow these safety instructions at all times.

Do not attempt to install or start up this equipment without first reading all documentation provided with the product. Read and understand these safety instructions and all user documentation of the equipment prior to working with the equipment at any time. If you do not have the user documentation for your equipment, contact your local Bosch Rexroth representative to send this documentation immediately to the person or persons responsible for the safe operation of this equipment.

If the equipment is resold, rented or transferred or passed on to others, then these safety instructions must be delivered with the equipment.

⚠️ **WARNING**	**Improper use of this equipment, failure to follow the safety instructions in this document or tampering with the product, including disabling of safety devices, may result in material damage, bodily harm, electric shock or even death!**

3.2   Explanations

The safety instructions describe the following degrees of hazard seriousness in compliance with ANSI Z535. The degree of hazard seriousness informs about the consequences resulting from non-compliance with the safety instructions.

Warning symbol with signal word	Degree of hazard seriousness according to ANSI
⚠️ **DANGER**	Death or severe bodily harm will occur.
⚠️ **WARNING**	Death or severe bodily harm may occur.
⚠️ **CAUTION**	Bodily harm or material damage may occur.

Fig. 3-1:   Hazard classification (according to ANSI Z535)

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3.3   Hazards by Improper Use

⚠ **DANGER**	**High voltage and high discharge current! Danger to life or severe bodily harm by electric shock!**
⚠ **DANGER**	**Dangerous movements! Danger to life, severe bodily harm or material damage by unintentional motor movements!**
⚠ **WARNING**	**High electrical voltage due to wrong connections! Danger to life or bodily harm by electric shock!**
⚠ **WARNING**	**Health hazard for persons with heart pacemakers, metal implants and hearing aids in proximity to electrical equipment!**
⚠ **CAUTION**	**Surface of machine housing could be extremely hot! Danger of injury! Danger of burns!**
⚠ **CAUTION**	**Risk of injury due to improper handling! Bodily harm caused by crushing, shearing, cutting and mechanical shock or incorrect handling of pressurized systems!**
⚠ **CAUTION**	**Risk of injury due to incorrect handling of batteries!**

3.4   General Information

- Bosch Rexroth AG is not liable for damages resulting from failure to observe the warnings provided in this documentation.

- Read the operating, maintenance and safety instructions in your language before starting up the machine. If you find that you cannot completely understand the documentation for your product, please ask your supplier to clarify.

- Proper and correct transport, storage, assembly and installation as well as care in operation and maintenance are prerequisites for optimal and safe operation of this equipment.

- Only persons who are trained and qualified for the use and operation of the equipment may work on this equipment or within its proximity.

  - The persons are qualified if they have sufficient knowledge of the assembly, installation and operation of the equipment as well as an understanding of all warnings and precautionary measures noted in these instructions.

  - Furthermore, they must be trained, instructed and qualified to switch electrical circuits and equipment on and off in accordance with technical safety regulations, to ground them and to mark them according to the requirements of safe work practices. They must have adequate safety equipment and be trained in first aid.

- Only use spare parts and accessories approved by the manufacturer.

- Follow all safety regulations and requirements for the specific application as practiced in the country of use.

- The equipment is designed for installation in industrial machinery.

- The ambient conditions given in the product documentation must be observed.

- Use only safety features and applications that are clearly and explicitly approved in the Project Planning Manual.
  For example, the following areas of use are not permitted: construction cranes, elevators used for people or freight, devices and vehicles to transport people, medical applications, refinery plants, transport of hazardous goods, nuclear applications, applications sensitive to high frequency, mining, food processing, control of protection equipment (also in a machine).

- The information given in the documentation of the product with regard to the use of the delivered components contains only examples of applications and suggestions.
  The machine and installation manufacturer must

  - make sure that the delivered components are suited for his individual application and check the information given in this documentation with regard to the use of the components,

  - make sure that his application complies with the applicable safety regulations and standards and carry out the required measures, modifications and complements.

- Startup of the delivered components is only permitted once it is sure that the machine or installation in which they are installed complies with the national regulations, safety specifications and standards of the application.

- Technical data, connections and operational conditions are specified in the product documentation and must be followed at all times.

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- Operation is only permitted if the national EMC regulations for the application are met.
  The instructions for installation in accordance with EMC requirements can be found in the documentation "EMC in Drive and Control Systems".
  The machine or installation manufacturer is responsible for compliance with the limiting values as prescribed in the national regulations.

3.5   Protection Against Contact with Electrical Parts

Note:	This section refers to equipment and drive components with voltages above 50 Volts.

Touching live parts with voltages of 50 Volts and more with bare hands or conductive tools or touching ungrounded housings can be dangerous and cause electric shock. In order to operate electrical equipment, certain parts must unavoidably have dangerous voltages applied to them.

DANGER

High electrical voltage! Danger to life, severe bodily harm by electric shock!

⇒ Only those trained and qualified to work with or on electrical equipment are permitted to operate, maintain or repair this equipment.

⇒ Follow general construction and safety regulations when working on high voltage installations.

⇒ Before switching on power the ground wire must be permanently connected to all electrical units according to the connection diagram.

⇒ Do not operate electrical equipment at any time, even for brief measurements or tests, if the ground wire is not permanently connected to the points of the components provided for this purpose.

⇒ Before working with electrical parts with voltage higher than 50 V, the equipment must be disconnected from the mains voltage or power supply. Make sure the equipment cannot be switched on again unintended.

⇒ The following should be observed with electrical drive and filter components:

⇒ Wait five (5) minutes after switching off power to allow capacitors to discharge before beginning to work. Measure the voltage on the capacitors before beginning to work to make sure that the equipment is safe to touch.

⇒ Never touch the electrical connection points of a component while power is turned on.

⇒ Install the covers and guards provided with the equipment properly before switching the equipment on. Prevent contact with live parts at any time.

⇒ A residual-current-operated protective device (RCD) must not be used on electric drives! Indirect contact must be prevented by other means, for example, by an overcurrent protective device.

⇒ Electrical components with exposed live parts and uncovered high voltage terminals must be installed in a protective housing, for example, in a control cabinet.

To be observed with electrical drive and filter components:

⚠ DANGER

High electrical voltage on the housing!
High leakage current! Danger to life, danger of injury by electric shock!

⇒ Connect the electrical equipment, the housings of all electrical units and motors permanently with the safety conductor at the ground points before power is switched on. Look at the connection diagram. This is even necessary for brief tests.

⇒ Connect the safety conductor of the electrical equipment always permanently and firmly to the supply mains. Leakage current exceeds 3.5 mA in normal operation.

⇒ Use a copper conductor with at least 10 mm² cross section over its entire course for this safety conductor connection!

⇒ Prior to startups, even for brief tests, always connect the protective conductor or connect with ground wire. Otherwise, high voltages can occur on the housing that lead to electric shock.

3.6 Protection Against Electric Shock by Protective Low Voltage (PELV)

All connections and terminals with voltages between 0 and 50 Volts on Rexroth products are protective low voltages designed in accordance with international standards on electrical safety.

⚠ WARNING

High electrical voltage due to wrong connections! Danger to life, bodily harm by electric shock!

⇒ Only connect equipment, electrical components and cables of the protective low voltage type (PELV = Protective Extra Low Voltage) to all terminals and clamps with voltages of 0 to 50 Volts.

⇒ Only electrical circuits may be connected which are safely isolated against high voltage circuits. Safe isolation is achieved, for example, with an isolating transformer, an opto-electronic coupler or when battery-operated.

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3.7 Protection Against Dangerous Movements

Dangerous movements can be caused by faulty control of the connected motors. Some common examples are:

- improper or wrong wiring of cable connections
- incorrect operation of the equipment components
- wrong input of parameters before operation
- malfunction of sensors, encoders and monitoring devices
- defective components
- software or firmware errors

Dangerous movements can occur immediately after equipment is switched on or even after an unspecified time of trouble-free operation.

The monitoring in the drive components will normally be sufficient to avoid faulty operation in the connected drives. Regarding personal safety, especially the danger of bodily injury and material damage, this alone cannot be relied upon to ensure complete safety. Until the integrated monitoring functions become effective, it must be assumed in any case that faulty drive movements will occur. The extent of faulty drive movements depends upon the type of control and the state of operation.

DANGER

Dangerous movements! Danger to life, risk of injury, severe bodily harm or material damage!

⇒ Ensure personal safety by means of qualified and tested higher-level monitoring devices or measures integrated in the installation. Unintended machine motion is possible if monitoring devices are disabled, bypassed or not activated.

⇒ Pay attention to unintended machine motion or other malfunction in any mode of operation.

⇒ Keep free and clear of the machine's range of motion and moving parts. Possible measures to prevent people from accidentally entering the machine's range of motion:
  - use safety fences
  - use safety guards
  - use protective coverings
  - install light curtains or light barriers

⇒ Fences and coverings must be strong enough to resist maximum possible momentum, especially if there is a possibility of loose parts flying off.

⇒ Mount the emergency stop switch in the immediate reach of the operator. Verify that the emergency stop works before startup. Don't operate the machine if the emergency stop is not working.

⇒ Isolate the drive power connection by means of an emergency stop circuit or use a starting lockout to prevent unintentional start.

⇒ Make sure that the drives are brought to a safe standstill before accessing or entering the danger zone. Safe standstill can be achieved by switching off the power supply contactor or by safe mechanical locking of moving parts.

⇒ Secure vertical axes against falling or dropping after switching off the motor power by, for example:

- mechanically securing the vertical axes

- adding an external braking/ arrester/ clamping mechanism

- ensuring sufficient equilibration of the vertical axes

The standard equipment motor brake or an external brake controlled directly by the drive controller are not sufficient to guarantee personal safety!

⇒ Disconnect electrical power to the equipment using a master switch and secure the switch against reconnection for:

- maintenance and repair work

- cleaning of equipment

- long periods of discontinued equipment use

⇒ Prevent the operation of high-frequency, remote control and radio equipment near electronics circuits and supply leads. If the use of such equipment cannot be avoided, verify the system and the installation for possible malfunctions in all possible positions of normal use before initial startup. If necessary, perform a special electromagnetic compatibility (EMC) test on the installation.

3.8 Protection Against Magnetic and Electromagnetic Fields During Operation and Mounting

Magnetic and electromagnetic fields generated near current-carrying conductors and permanent magnets in motors represent a serious health hazard to persons with heart pacemakers, metal implants and hearing aids.

WARNING

Health hazard for persons with heart pacemakers, metal implants and hearing aids in proximity to electrical equipment!

⇒ Persons with heart pacemakers, hearing aids and metal implants are not permitted to enter the following areas:

- Areas in which electrical equipment and parts are mounted, being operated or started up.

- Areas in which parts of motors with permanent magnets are being stored, operated, repaired or mounted.

⇒ If it is necessary for a person with a heart pacemaker to enter such an area, then a doctor must be consulted prior to doing so. Heart pacemakers that are already implanted or will be implanted in the future, have a considerable variation in their electrical noise immunity. Therefore there are no rules with general validity.

⇒ Persons with hearing aids, metal implants or metal pieces must consult a doctor before they enter the areas described above. Otherwise, health hazards will occur.

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3.9   Protection Against Contact with Hot Parts

CAUTION

Housing surfaces could be extremely hot!
Danger of injury! Danger of burns!

⇒ Do not touch housing surfaces near sources of heat! Danger of burns!

⇒ After switching the equipment off, wait at least ten (10) minutes to allow it to cool down before touching it.

⇒ Do not touch hot parts of the equipment, such as housings with integrated heat sinks and resistors. Danger of burns!

3.10   Protection During Handling and Mounting

Under certain conditions, incorrect handling and mounting of parts and components may cause injuries.

CAUTION

Risk of injury by incorrect handling! Bodily harm caused by crushing, shearing, cutting and mechanical shock!

⇒ Observe general installation and safety instructions with regard to handling and mounting.

⇒ Use appropriate mounting and transport equipment.

⇒ Take precautions to avoid pinching and crushing.

⇒ Use only appropriate tools. If specified by the product documentation, special tools must be used.

⇒ Use lifting devices and tools correctly and safely.

⇒ For safe protection wear appropriate protective clothing, e.g. safety glasses, safety shoes and safety gloves.

⇒ Never stand under suspended loads.

⇒ Clean up liquids from the floor immediately to prevent slipping.

3.11 Battery Safety

Batteries contain reactive chemicals in a solid housing. Inappropriate handling may result in injuries or material damage.

> ⚠️ **CAUTION**
>
> **Risk of injury by incorrect handling!**
> ⇒ Do not attempt to reactivate discharged batteries by heating or other methods (danger of explosion and cauterization).
> ⇒ Never charge non-chargeable batteries (danger of leakage and explosion).
> ⇒ Never throw batteries into a fire.
> ⇒ Do not dismantle batteries.
> ⇒ Do not damage electrical components installed in the equipment.

Note: Be aware of environmental protection and disposal! The batteries contained in the product should be considered as hazardous material for land, air and sea transport in the sense of the legal requirements (danger of explosion). Dispose batteries separately from other waste. Observe the legal requirements in the country of installation.

3.12 Protection Against Pressurized Systems

Certain motors and drive controllers, corresponding to the information in the respective Project Planning Manual, must be provided with pressurized media, such as compressed air, hydraulic oil, cooling fluid and cooling lubricant supplied by external systems. Incorrect handling of the supply and connections of pressurized systems can lead to injuries or accidents. In these cases, improper handling of external supply systems, supply lines or connections can cause injuries or material damage.

> ⚠️ **CAUTION**
>
> **Danger of injury by incorrect handling of pressurized systems !**
> ⇒ Do not attempt to disassemble, to open or to cut a pressurized system (danger of explosion).
> ⇒ Observe the operation instructions of the respective manufacturer.
> ⇒ Before disassembling pressurized systems, release pressure and drain off the fluid or gas.
> ⇒ Use suitable protective clothing (for example safety glasses, safety shoes and safety gloves)
> ⇒ Remove any fluid that has leaked out onto the floor immediately.

Note: Environmental protection and disposal! The media used in the operation of the pressurized system equipment may not be environmentally compatible. Media that are damaging the environment must be disposed separately from normal waste. Observe the legal requirements in the country of installation.

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Notes

4 Projecting and Programming

4.1 Overview

Requirements To project an IndraLogic VPP 21 the installation of "IndraWorks Logic" is required. The installation program is available on CD-ROM. During the installation also the required target information (Target Support Package) of the IndraLogic VPP 21 are transferred to the target computer.

Processing Steps The project planning process is divided into the following steps:

- Project planning and I/O configuration with IndraWorks
- PLC program generation with IndraLogic
- Download and Commissioning
- Operation, visualization and diagnosis with IndraWorks HMI and IndraWorks WinStudio, see /5/.

4.2 Projecting with IndraWorks

Start IndraWorks

IndraWorks can be started by clicking on the desktop icon "IndraWorks Engineering" or via "Start, Program Files, Rexroth, IndraWorks, Engineering" (see figure below).
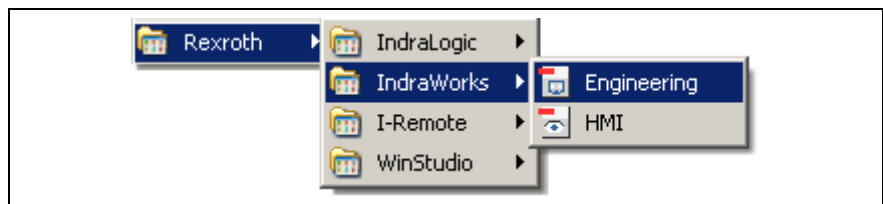

Fig. 4-1:   Start IndraWorks

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Create New IndraLogic VPP 21 Project

For further information refer to the documentation or online help of IndraWorks /5/.

A new project can be created with menu function "File", "New", "Project". A dialog box appears, in which the project name can be entered.
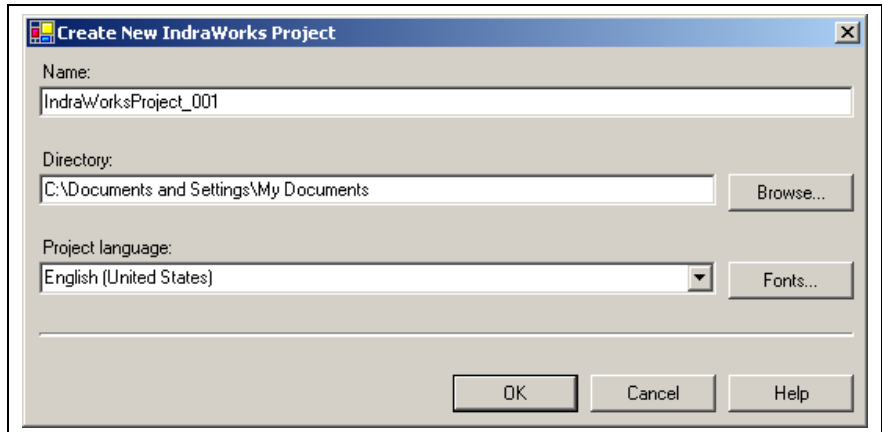
Fig. 4-2:   Create new project

The IndraLogic VPP 21 can be inserted per Drag & Drop from the device library under "Rexroth", "Drive and Control" in the current IndraWorks project.
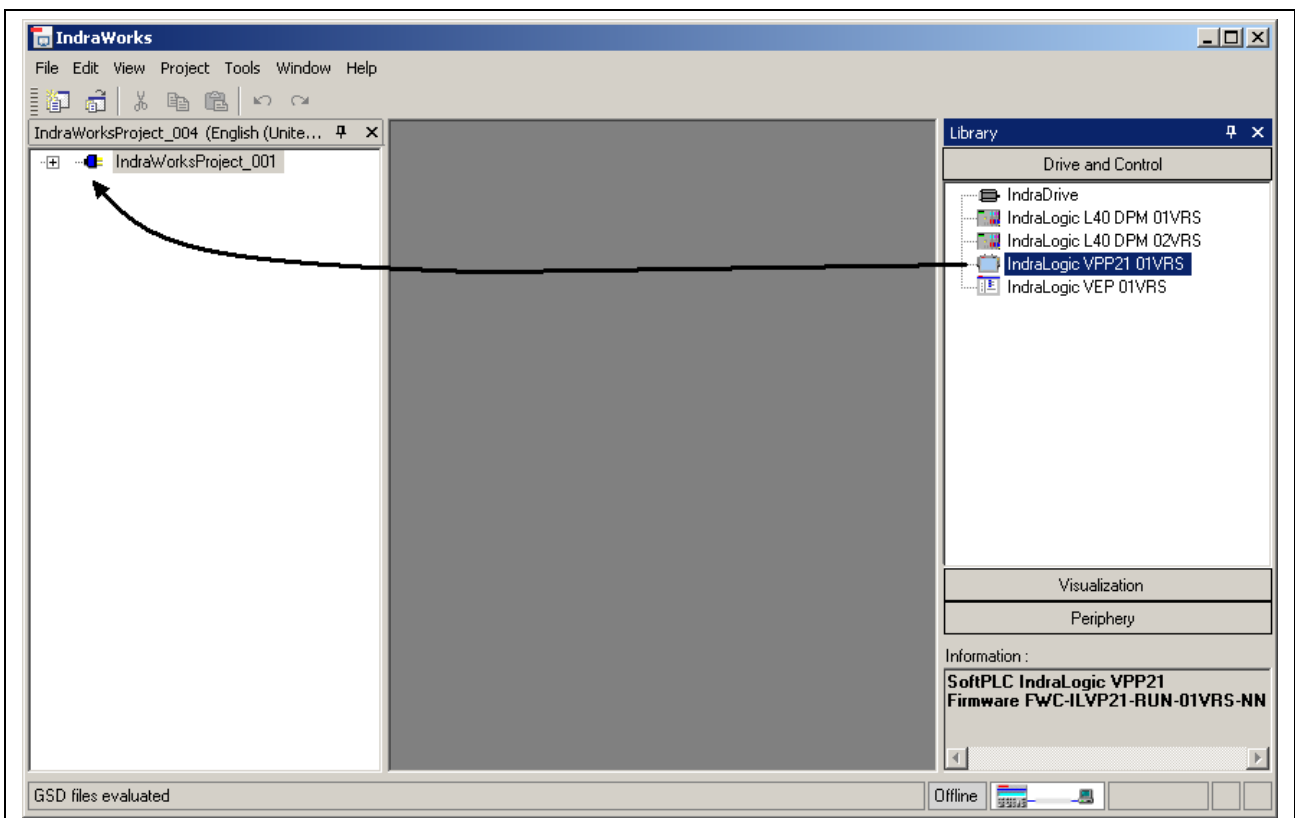

Fig. 4-3:   Inserting the IndraLogic VPP 21 into the project explorer

After inserting a device in the project explorer a wizard appears, with which the project settings can be changed, see "Inputs in the Wizard".

Then, the device is integrated in the project explorer

The following figure shows a completely configured and programmed IndraLogic VPP 21 project example:
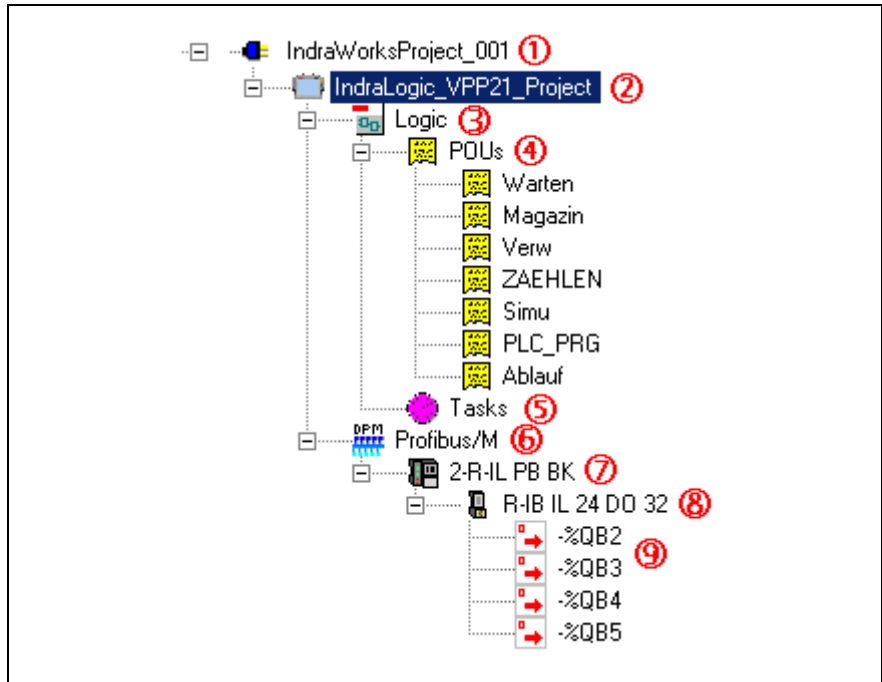
(1)   IndraWorks project
(2)   Device name
(3)   Logic object node (PLC project)
(4)   PLC blocks (POU)
(5)   PLC task management
(6)   Profibus DP master
(7)   DP slave at the Profibus DP master
(8)   Module of the DP slave
(9)   PLC addresses of the slave module, here outputs
Fig. 4-4:   Example: IndraLogic VPP 21 in the project explorer

Inputs in the Wizard

Device Settings The device settings contain general data of the IndraLogic project.

Fig. 4-5:   Device settings

If required, the device name can be changed. The device name is indicated in the project explorer. Furthermore, you can enter any comment about the device. The inputs are confirmed via the "Next >>" button, then dialog box "Communication Parameters" appears.

Communication Settings Here, the settings for the communication between IndraWorks and the IndraLogic VPP 21 can be assigned. To open this dialog the IndraLogic Gateway server is automatically started, when it is not already active.

In the following dialog box of the communication settings you can select the available channels (communication instances) and thus assign these channels to the current IndraLogic VPP 21 project:
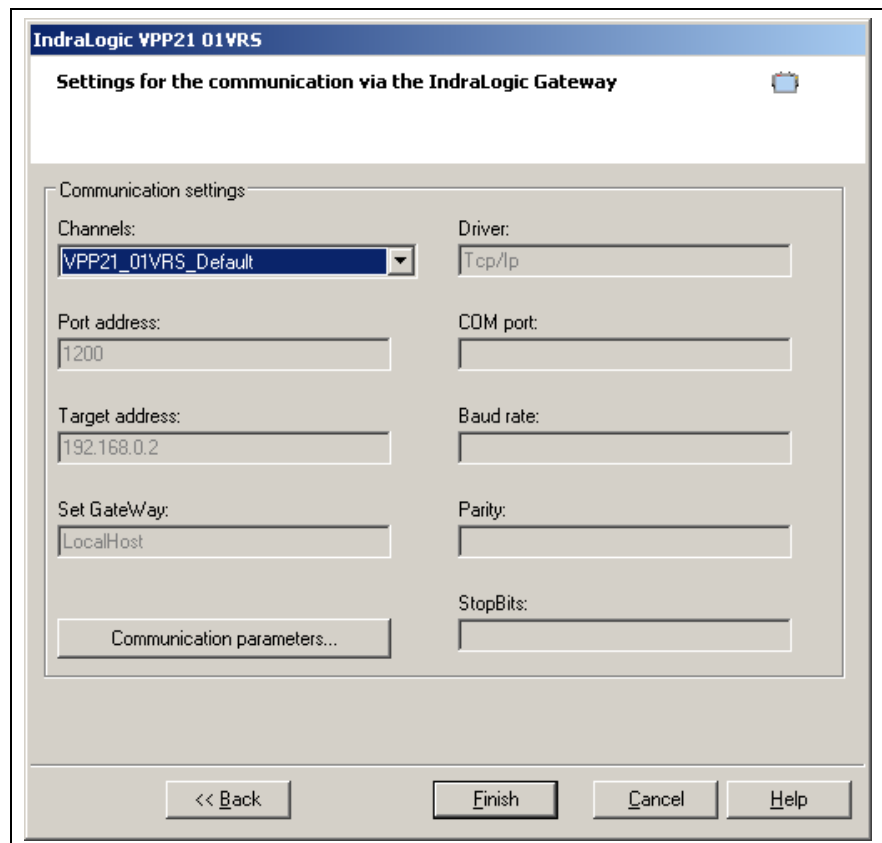
Fig. 4-6:   Communication settings

In this dialog box you can determine, if you want to engineer locally on the IndraControl VPP 21 or on another PC (remote programming).

Local Communication   If IndraWorks is directly installed on the operator terminal IndraControl VPP 21, the local communication channel "VPP 21_xxVRS_Default" can be used. This channel is already available by default.

The inputs are confirmed via the "Finish" button. Then, an IndraLogic VPP 21 project is created in the project explorer.

Remote Programming   If IndraWorks is not installed on the operator terminal IndraControl VPP 21, but on another PC (remote programming), you must establish a connection to the Gateway server of the target computer.

1. Start the Gateway server on the target computer: "Start, Program Files, Rexroth, IndraLogic, Communication"

2. Start the software PLC "SoftPanel" on the target computer.

3. Use communication channel "VPP 21_xxVRS_Default" on the remote computer, see Fig. 4-6.

4. Adapt the parameters on the remote computer with the "Communication parameters" button. A dialog box appears. If there still exist no entries, see Fig. 4-7, then confirm "New..." and enter a name for the connection. After that, double-click on entry "localhost" and overwrite it. Enter the IP address "192.168.0.2" and finish the input with "Enter", see Fig. 4-8.

5. Confirm "Gateway...". A dialog box to enter the Gateway parameters appears, see Fig. 4-9. Select here the "TCP/IP" connection and enter the IP address of the target computer. Confirm all entries with "OK".

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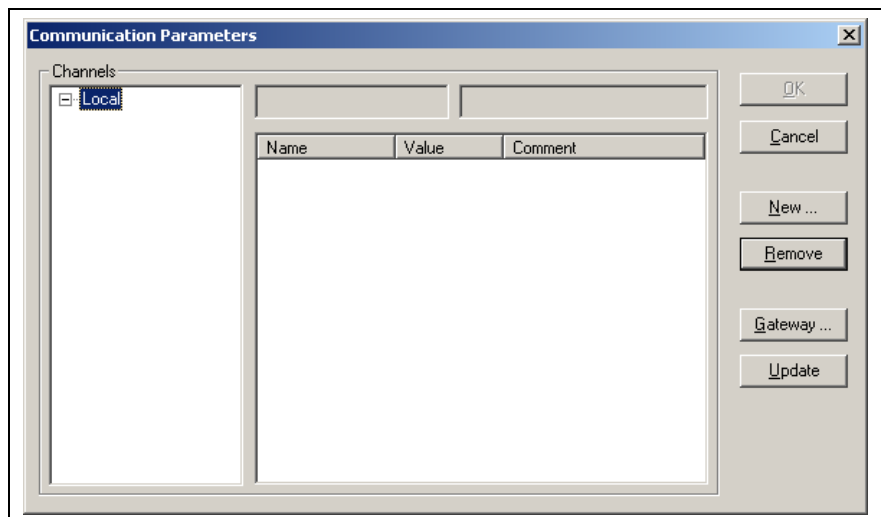
Fig. 4-7:   IndraLogic communication parameters (empty)
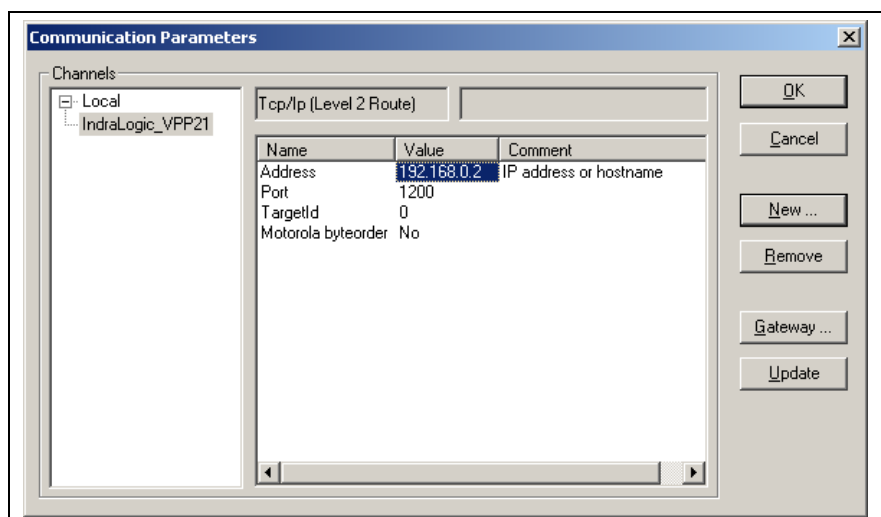
Fig. 4-8:   IndraLogic communication parameters
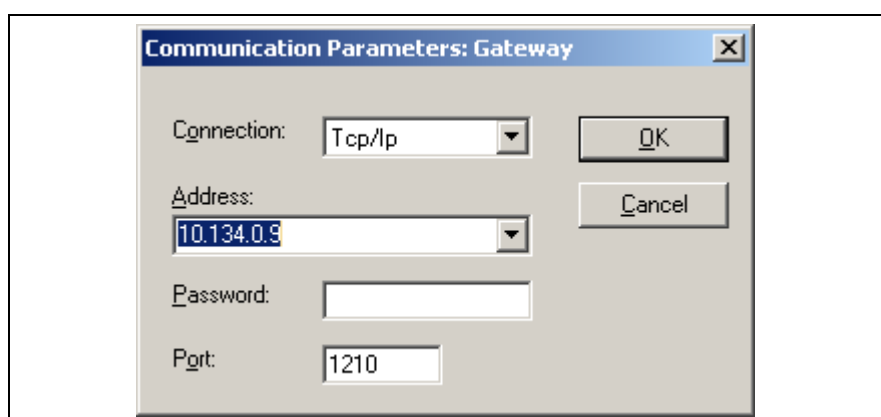
Fig. 4-9:   IndraLogic Gateway

You will find further information help about the topic "Communication parameters" in the IndraLogic help, or in the IndraLogic manual /2/.

Change Settings   The settings can be changed subsequently via the context menu (right mouse key):
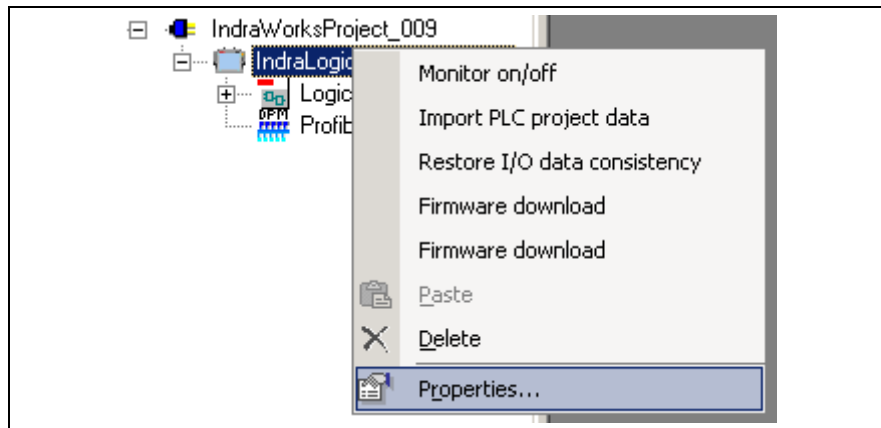
Fig. 4-10:   Context menu, device properties of the IndraLogic VPP 21
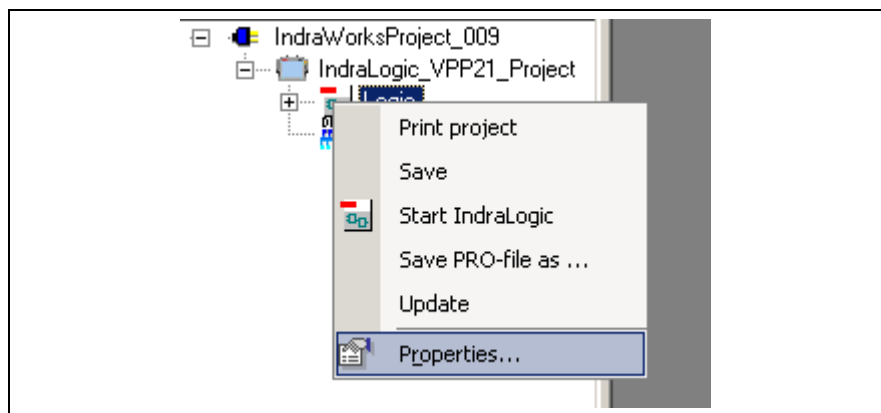
Fig. 4-11:   Context menu, communication properties of the IndraLogic VPP 21

Further Information   For further information refer to chapter 5 and to the documentation or online help of IndraWorks /5/.

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Configuring Profibus DP

The IndraLogic VPP 21 provides a PROFIBUS DP interface with bus master functionality according to DIN EN 50170, Part 2. The Profibus configuration provides the following features:

- Slave configuration
- Processing vendor-specific data
- Modifying bus-specific settings

After finishing the Profibus configuration the data are transferred to the target device with the help of IndraLogic.

Note: Changed settings are only activated in the PLC with the next download, see section "Download and Commissioning"!

Master Settings

Operation parameters of the bus system can be defined for Profibus DP. For this, open the master information by double-clicking on node "Profibus/M" in the project explorer.

(1)   Master settings
(2)   Bus parameters
(3)   Optimization
(4)   Groups
(5)   Parameters

Fig. 4-12:   Master settings

Master Settings (1)   The following data are indicated. Some data can be changed:

Name: Device name of the internal bus master of the IndraLogic VPP 21

Based on: Ident number according to the GSD file

SW version: Software version according to the GSD file

HW version: Hardware version according to the GSD file

Bus address: Here, bus address 1 (FDL address) is automatically entered. The address can be overwritten or modified by means of key "...". Address 0 is reserved for engineering devices and cannot be used here.

Note:	Always use bus addresses being as low as possible for the master, as for high bus addresses the bus performance (concerning the token ring management) deteriorates.

Comment: Please enter here any comment about the master.

Bus Parameters (2)(3)

The bus parameters important for the operation of the Profibus DP are indicated here. If the **Optimization** (3) is set to **Default**, only the boxes "Baud rate" and "Max. retry limit" can be edited. All other parameters are default values, that are optimized to the current baud rate. These default values correspond to a recommendation of the Profibus user organization and is suitable for the majority of applications. Only for special exceptional cases it is necessary to modify a few parameters manually. For this, activate the **Optimization: Manually** (in preparation).

⚠ CAUTION	**Modifications of the default bus parameters can cause an unpredictable behavior of the Profibus DP!**
	⇒ The bus parameters may only be modified by instructed Profibus DP specialists, who are aware of the effects of this modifications!

Groups (4)

Not available!

Parameters (5)

Here, vendor-specific parameters of the master can be displayed or edited.

Parameter "EnableDiags" of the IndraLogic VPP 21 has no function.

Select with parameter "Byteorder Wordmodules Motorola", if the arrangement of high and low byte for word modules is to be provided in Motorola format (Yes) or in Intel format (No). For Rexroth Inline-Module as of word seize (e. g. analog modules) please select "Yes".

Select with parameter "IO Handling", if the complete data of the I/O image are to be provided consistently (Data Consistency) or not (No Data Consistency: Recommended setting).

Note:	Changed settings are only activated in the PLC with the next download, see section "Download and Commissioning"!

Further Information

For further information refer to the documentation or online help of IndraWorks /5/.

Inserting Slaves

All Profibus DP slaves provided for the IndraLogic VPP 21 are archived in the device library under "Periphery", "Profibus DP". Insert a slave from the device library per Drag & Drop below the object node "Profibus/M" in the project explorer. New slaves can be positioned between already inserted slaves.

Additional slaves can be archived in the device library by means of GSD files. For further information refer to the documentation or online help of IndraWorks /5/.
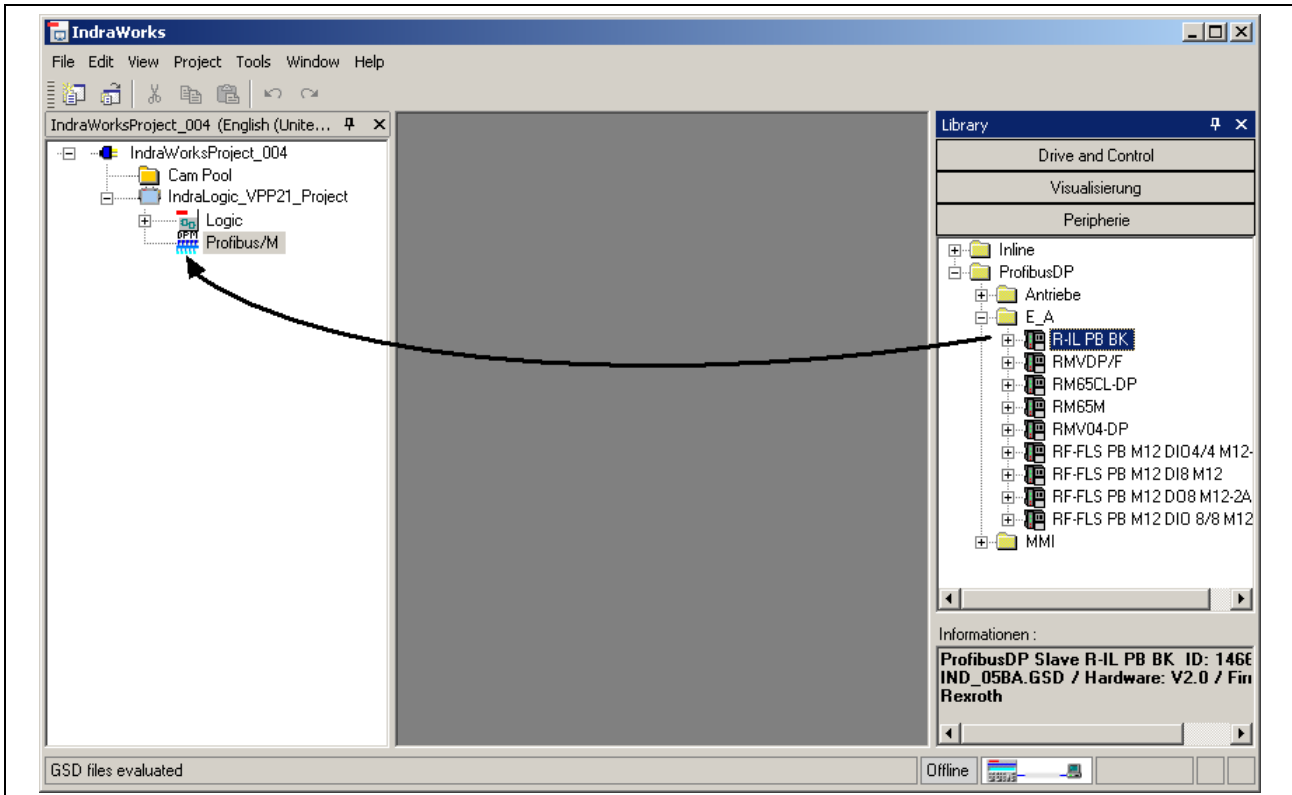
Fig. 4-13:   Insert Profibus DP slave

While inserting a slave in the project explorer, the general slave data are indicated in a dialog box (wizard). Some data can be changed.

All entries made in the wizard can be also changed later, see the following figure. For this, double-click on the desired slave in the project explorer.
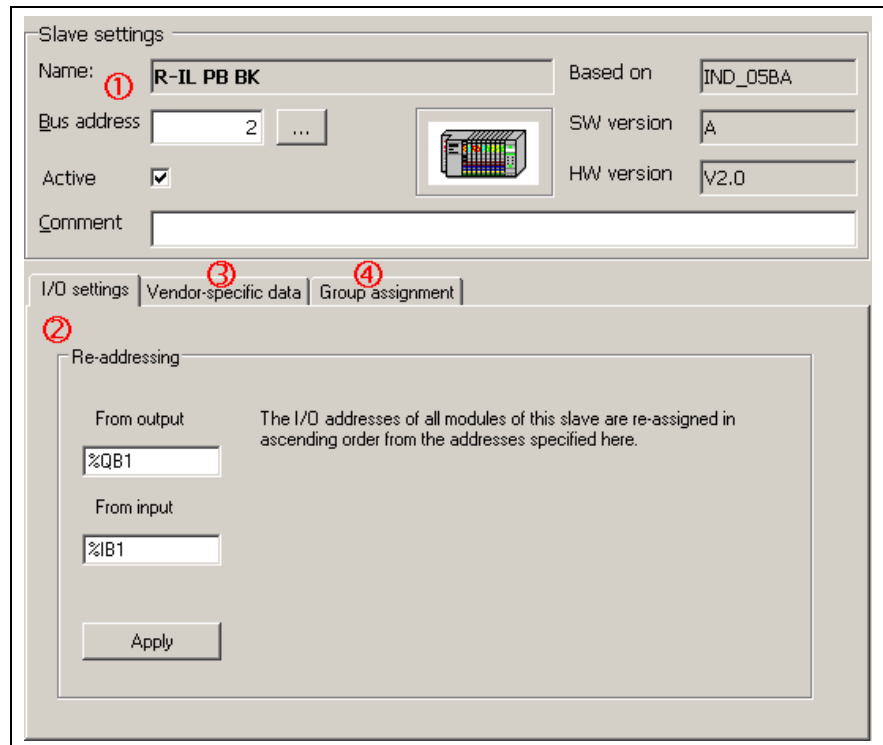
(1)	Slave settings
(2)	Automatic addressing
(3)	Vendor-specific data
(4)	Group assignment

Fig. 4-14:   Slave settings

Slave Settings (1)   **Name:** Device name of the slave according to the GSD file

Based on: Ident number according to the GSD file

SW version: Software version according to the GSD file

HW version: Hardware version according to the GSD file

Bus address: Here, the next free bus address (FDL address) is automatically entered. The address can be overwritten or modified by means of key "...".

The bus address of the slave is also displayed in the project explorer. It is set in front of the slave name.

Example, see figure below: Slave "R-IL PB BK" with bus address 2 is indicated in the project explorer as "**2**-R-IL PB BK".

Active: Activate this option, so that the slave is transferred to the master parameter set and thus prepared for the operation at the Profibus for the next download. Deactivate this option to configure and archive the slave, but it is not commissioned at the Profibus. The switch-over Active/Passive can be also executed in the project explorer at the slave, see figure below.

(A)	Slave is in operation
(B)	Slave is not in operation

Fig. 4-15:   Active/Passive switch-over in the project explorer

Note: Changed settings are only activated in the PLC with the next download, see section "Download and Commissioning"!

Comment: Please enter here any comment about the device.

I/O Settings (2)   The modules can be automatically addressed in consecutive order. Enter the desired start address in the input box **From output** or **From input**. The automatic addressing is started with **Apply**. Thereby, all modules are sequentially provided with PLC addresses in consecutive order. In the event of address overlappings with already assigned addresses the next connected free address area is searched. In this case a dialog box appears with the request, if this free area is to be used for the addressing. The new addresses are applied to column "Address" of the module data.

The addressing can also be executed manually in the module data or can be modified subsequently, see "Inserting Modules".

Vendor-Specific Data (3)   With the "Vendor-specific data" tab further data can be displayed or edited. For further information refer to the documentation or online help of IndraWorks /5/.

Group Assignment (4)   Not available!

Inserting Modules

Profibus DP distinguishes between two slave types:

- **Compact:** A compact slave has a firmly defined module structure.

- **Modular:** However, for a modular slave the modules can be individually assigned depending on the fitting specification.

After inserting a slave in the project explorer (see "Inserting Slaves") the modules below the slave object node are already completely available because of the compact design of the slaves. However, for modular slaves the modules have to be manually assigned.

The modules suitable for the respective slave are archived in the device library below the slave ("+" opens the module list). Insert a module from the device library per Drag & Drop below the slave in the project explorer. New modules can be positioned between already inserted modules.
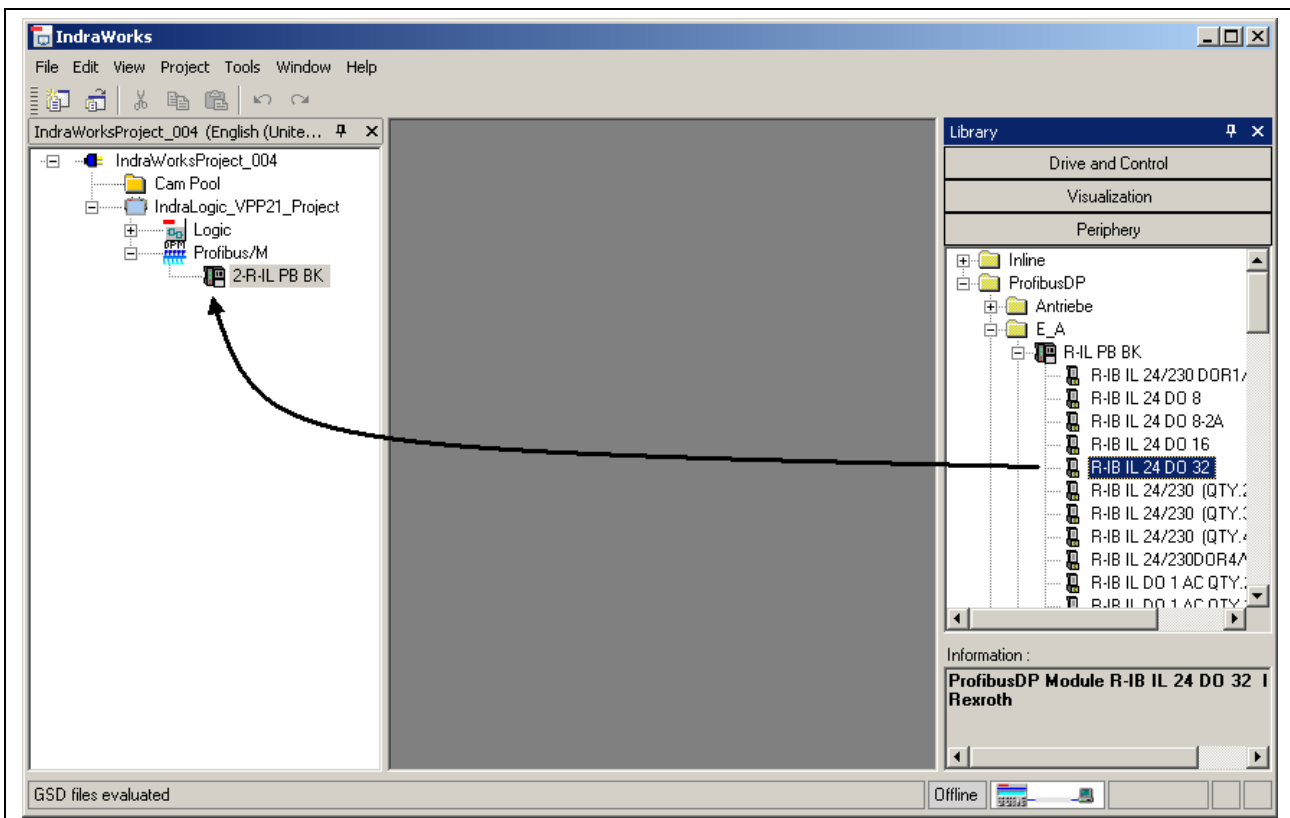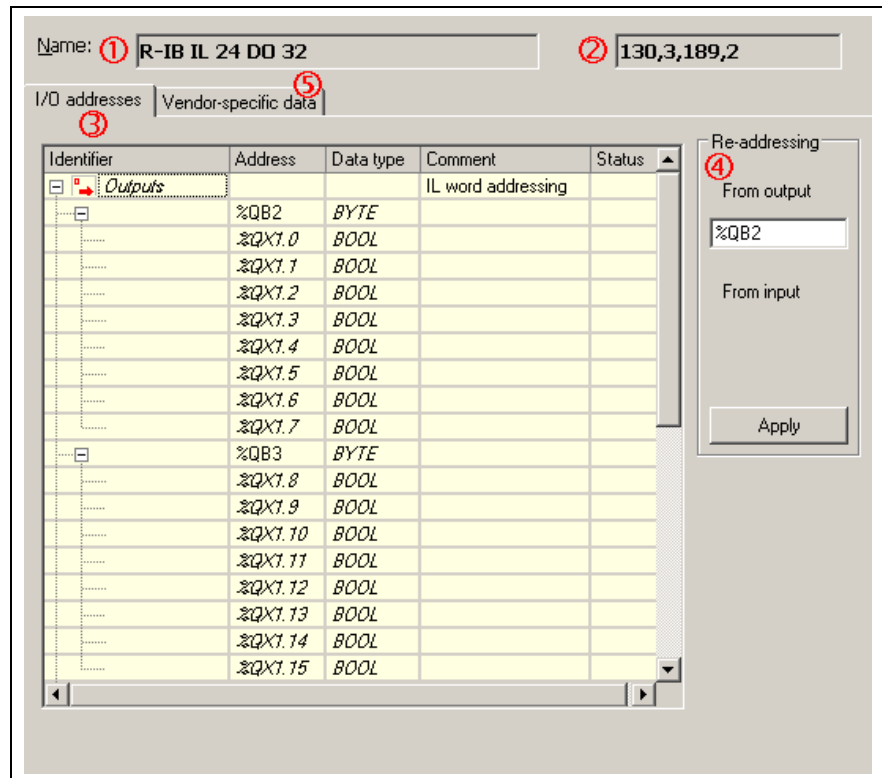

Fig. 4-16:   Inserting a Profibus slave module

While inserting a slave module in the project explorer, the module data are indicated in a dialog box (wizard). Some data can be changed.

All entries made in the wizard can be also changed later, see figure below. For this, double-click on the desired module in the project explorer.

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(1)   Module name
(2)   Internal module identification
(3)   I/O addresses
(4)   Automatic addressing
(5)   Vendor-specific data

Fig. 4-17:   Module data

Name (1)   Module name according to the GSD file

Configuration Bytes (2)   Internal module identification: Extract from the GSD file

I/O Addresses (3)   The I/O areas of the modules are assigned to the physical addresses (I/O addresses of the PLC).

Identifier: This column shows the individual input and output modules. With symbol +/– the bitwise illustration can be shown or hidden. Furthermore, a symbolic identifier can be assigned. The variable name, that shall be classified in the PLC project as global variable, is entered as symbolic address.

Example: The figure shows the symbolic identifiers Output01 and Output02. They are assigned to the byte addresses %QB2 and %QB3, see column "Address". This outputs can be addressed in the PLC project (IndraLogic) via the names Output01 or Output02.

Address: Here, the I/O address can be edited bytewise (e. g. %QB4). The bit addresses indicated in italics serve only for display and cannot be edited.

Comment: Please enter here any comment.

Status: Here, the real physical status of the input or output in the diagnostic mode is displayed (in preparation).

Re-addressing (4)   The modules can also be automatically addressed in consecutive order. Enter the desired start address in the input box **From output** or **From input**. The automatic addressing is started with **Apply**. Thereby, all modules are sequentially provided with PLC addresses in consecutive order. In the event of address overlappings with already assigned addresses the next connected free address area is searched. In this case a dialog box appears with the request, if this free area is to be used for the addressing. The new addresses are applied to column "Address".

Vendor-Specific Data (5)   With the "Vendor-specific data" tab further data can be displayed or edited. For further information refer to the documentation or online help of IndraWorks /5/.

Sync and Freeze Functions

The IndraLogic VPP 21 does not support any sync and freeze function of Profibus DP!

4.3   PLC Programming with IndraLogic

Overview

For the PLC project planning the following functions can be executed via program IndraLogic integrated in IndraWorks:

- Task Configuration: Control of the program processing
- PLC Configuration: The PLC configuration is not generated within IndraLogic, but in IndraWorks.
- Library Manager: Managing PLC block libraries
- Create a PLC Program: Creating blocks in PLC programming languages.

The PLC project planning with IndraLogic is activated via the object node "Logic" in the project explorer.
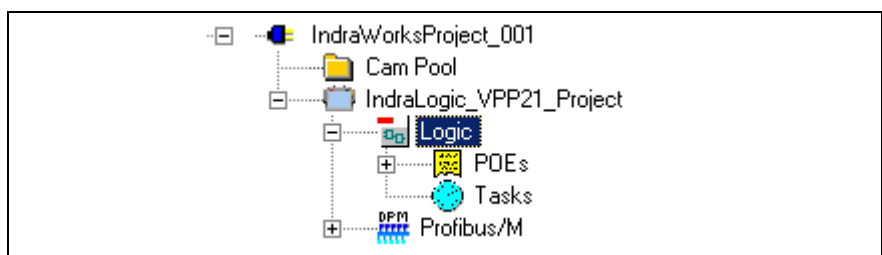
Fig. 4-18:   Logic node in the project explorer

- By double-clicking on "Logic" IndraLogic is started with the target system "IndraLogic VPP 21".
- By double-clicking on an entry below "POUs" (e. g. PLC_PRG) the corresponding block is opened in IndraLogic for further editing, see "Create a PLC Program".
- By double-clicking on "Tasks" the task configuration is started in IndraLogic, see "Task Configuration".

Update Project   All blocks generated in IndraLogic as well as the modifications of the settings are applied in the IndraWorks project explorer as soon as the context menu function "Update" is selected in the object node "Logic":
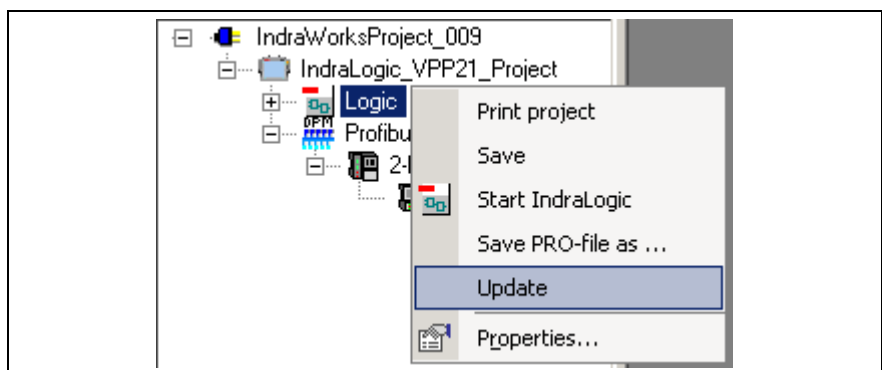
Fig. 4-19:   Update logic node

Task Configuration

For most of the application cases it is sufficient to execute the program without special task management. But it is possible to control the project execution via so-called tasks.

If you do not use a special task configuration, the program is processed via the main program PLC_PRG. PLC_PRG is automatically generated as block of type program. PLC_PRG is called up exactly one time in each control cycle.

The task configuration can be called by

- double-clicking on "Tasks" in the object node "Logic" in the IndraWorks project explorer

- or -

- by clicking on "Task configuration" in register "Resources" in IndraLogic.
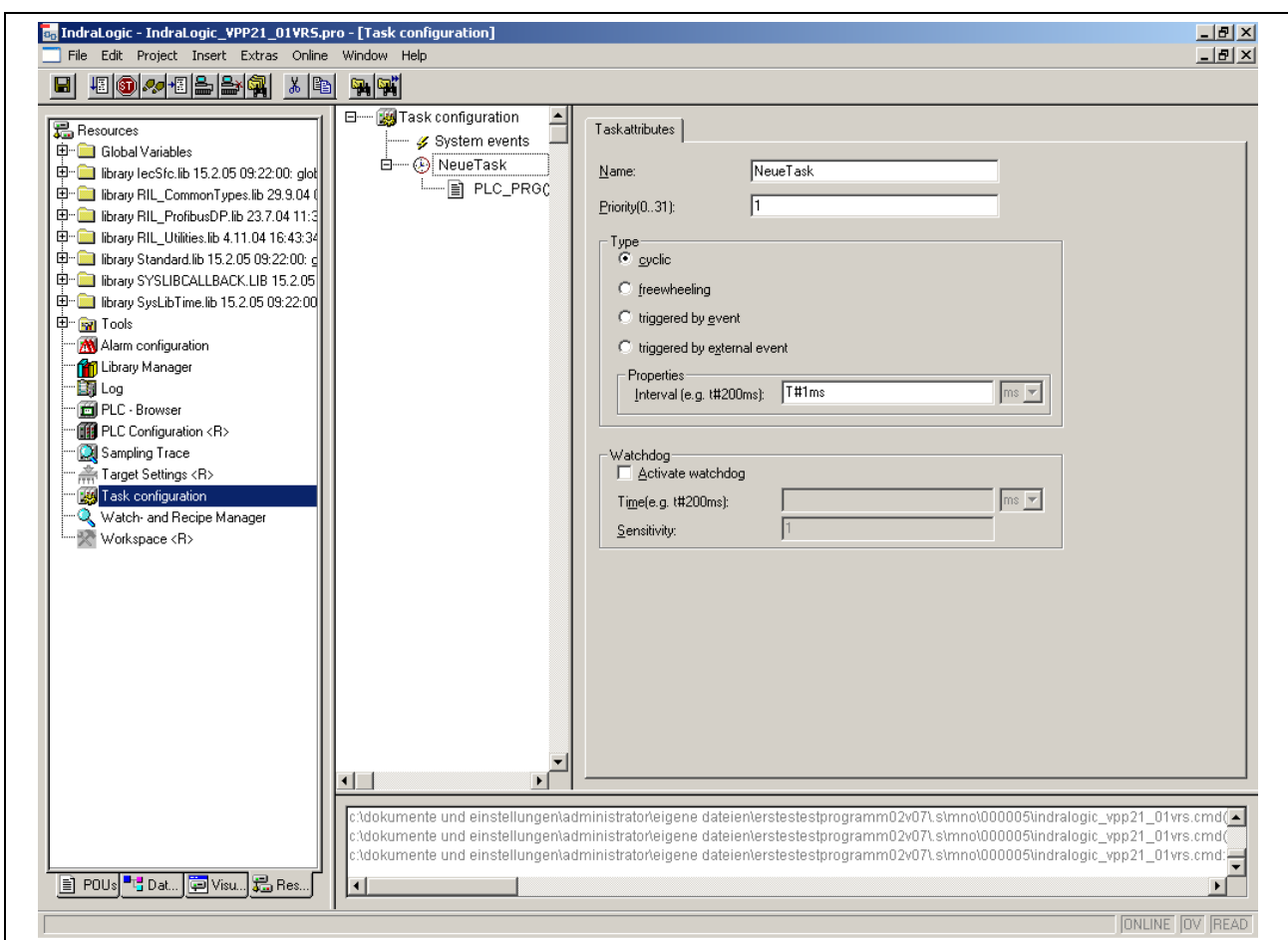
Fig. 4-20:   IndraLogic task configuration

For further information about the task attributes refer to the documentation or online help of IndraLogic /2/.

PLC Configuration

The PLC configuration is not generated within IndraLogic, but in IndraWorks. All input boxes of the IndraLogic PLC configuration are deactivated and cannot be changed.

Concerning the PLC configuration please consider section "Projecting with IndraWorks".

Library Manager

For further information about the library manager refer to the documentation or online help of IndraLogic /2/.

For information about the libraries of the IndraLogic VPP 21 refer to section "Libraries".

With the IndraLogic VPP 21 already a few libraries are indicated in IndraLogic in register "Resources". To link further libraries with the current project, menu function "Insert, Further library" is provided. After calling up this function, a file selection dialog indicating the current IndraWorks project path appears, see figure below:
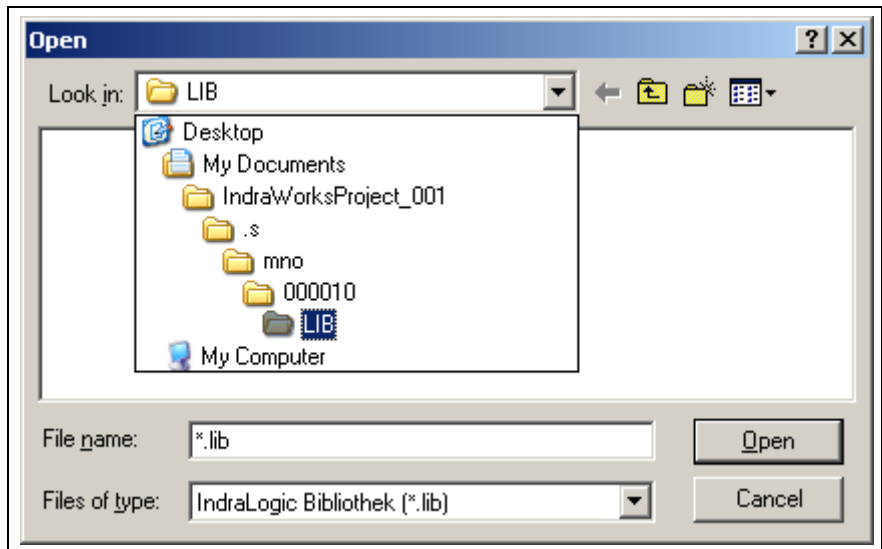
Fig. 4-21: Insert, Further library: IndraWorks project path

Select here the library directory of the installed target files of the IndraLogic VPP 21. The target files can be found in a sub-directory of the IndraWorks installation:

...\IndraWorks\IndraLogic\Targets

Example Example for the library directory of the IndraLogic VPP 21 01VRS (see also figure below).

C:\Program Files\Rexroth\IndraWorks\IndraLogic\Targets\
IndraLogic_VPP21_DPM_02VRS\lib\
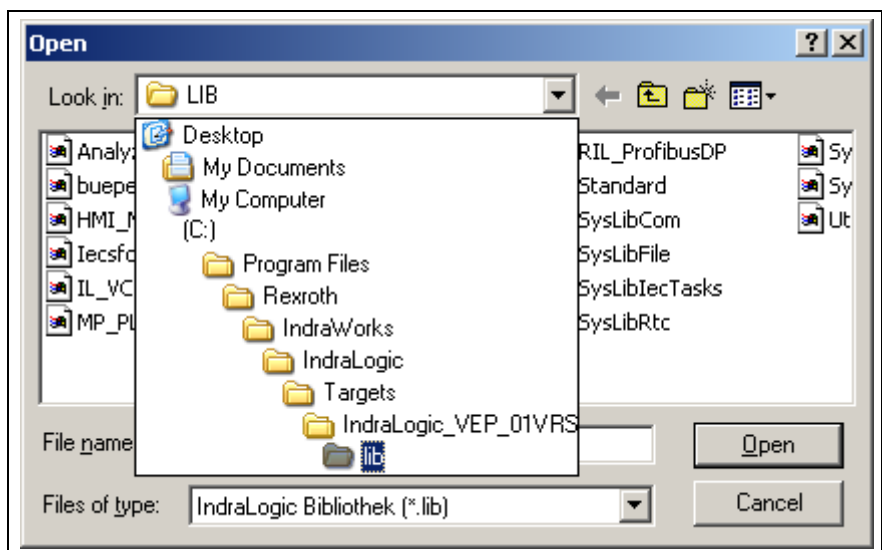
Fig. 4-22: Library directory of the IndraLogic VPP 21 target

Create a PLC Program

Create the PLC program in IndraLogic.

For further information refer to the documentation or online help of IndraLogic /2/.

To create compatible IEC programs, please observe the following chapter 4.4.
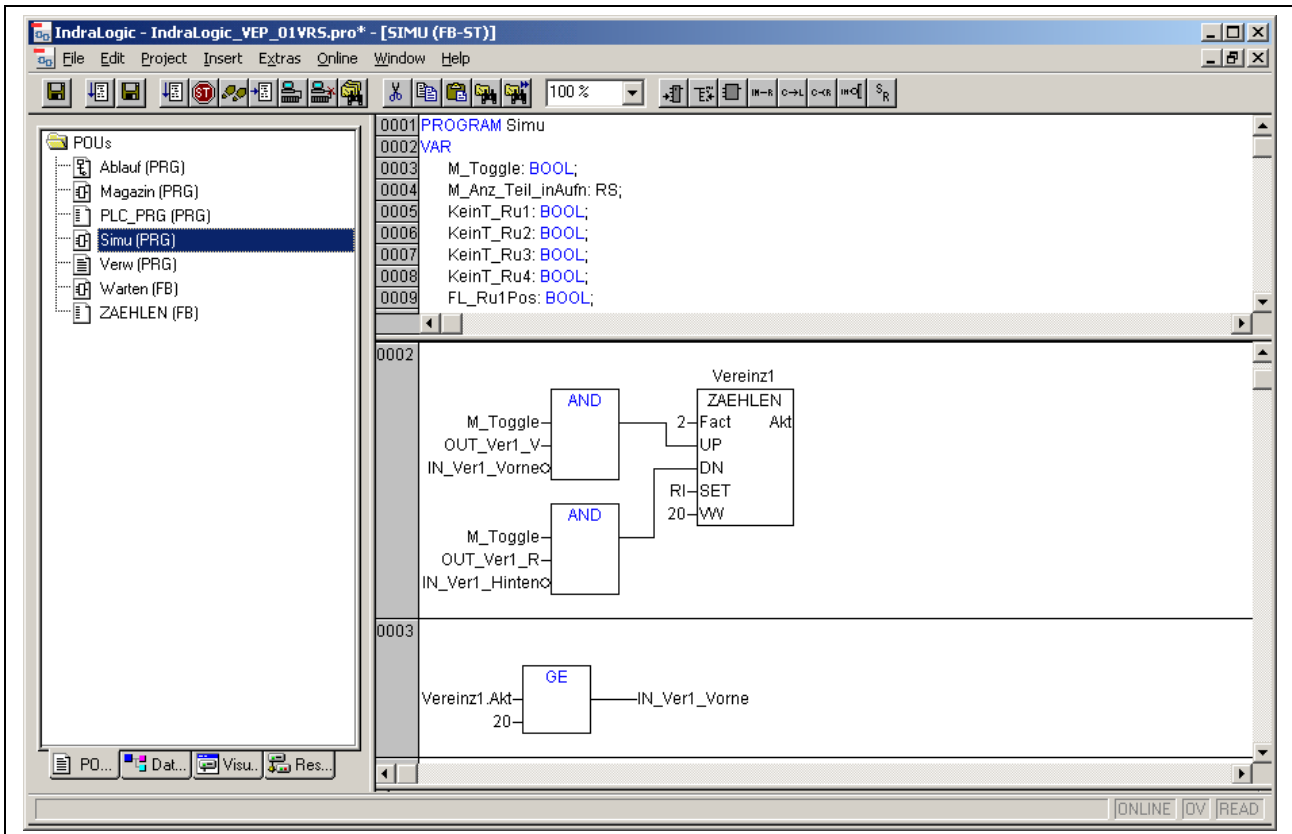
Fig. 4-23:   PLC program example

Save IndraLogic Project Data

With menu function "File, Save" all settings executed in IndraLogic and all edited blocks can be saved.

Note:	Always save the IndraLogic project data at first, before you change the current project in IndraWorks.

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4.4   Compatible IEC Programming between Different Controls

Overview

To ensure a compatible programming between the systems, consider the following features: It is described, which programming methods can be used, so that no incompatibilities may occur and, thus, the programs can be ported between the systems:

- Use of pointers within structures
- Memory alignment for I/O addresses, compatibility to the IndraControl L20.

Use of Pointers within Structures

If structures are created in the IEC program, the compiler maps this structures during the compilation process in the data memory of the control. The compiler recognizes exactly the possible restrictions of the used processor platform and archives the elements of the structure in the memory by using only addresses, that the processor can utilize for the corresponding data types.

If structures with elements containing different data types are created, the compiler inserts, e. g., for the IndraControl L20 filling bytes, that are not visible for the user.

```
TYPE OutStruct :
STRUCT
      Out01 : BYTE;
      Out02 : WORD;
      Out03 : BYTE;
      Out04 : DWORD;
END_STRUCT
END_TYPE
```

Fig. 4-24: Example of a structure declaration in the IEC program

Depending on the platform this structure is mapped to the memory as follows (here a comparison between the controls IndraLogic VPP 21 and L20):

IndraLogic VPP 21	**IndraControl L20**
ADR0 Out01 : BYTE; ADR1 Out02 : WORD; ADR3 Out03 : BYTE; ADR4 Out04 : DWORD; ADR8 :	ADR0 Out01 : BYTE; ADR1 (filling byte) ADR2 Out02 : WORD; ADR4 Out03 : BYTE; ADR5 (filling byte) ADR6 (filling byte) ADR7 (filling byte) ADR8 Out04 : DWORD; ADR12 :

Fig. 4-25:   Mapping of the memory

The structure elements are differently mapped, so that a compatible programming method being independent of the control's mapping must be used when accessing the structure elements.

Permissible Addressing   The compatible use of structures provides for a direct addressing of the elements via the point operator:

```
Structure name.Element name := Element value;
```

If the address of a structure is to be transferred to subfunctions via a pointer, the addressing of the elements is also only permissible by the offset calculation of the compiler:

```
Structure pointer^.Element name := Element value;
```

```
StructInst : OutStruct;              (* Declaration structure instance *)
pt : POINTER TO StructInst;          (* Declaration pointer to structure instance *)

StructInst.Out03 := 2#11110000;      (* Access to structure element *)

pt := ADR (StructInst);              (* Pointer initialization *)
pt^.Out02 := 16#FF00;                (* Access to structure element by pointer *)
```

Fig. 4-26: Examples

Impermissible Addressing   The addressing of a structure element by calculations in the code is **impermissible**:

```
Structure    element    pointer    :=    ADR    (Structure
name.Element);
```

```
Structure element pointer := Structure element pointer
+ n;
```

```
Structure element pointer^ := value;
```

This is impermissible and causes incompatibilities, as it is not ensured, that the offset creation to address a structure element by calculation in the code is reliable. The number of filling bytes is different for the platforms.

Alignment for I/O Addresses (IndraControl L20)

Please consider the following notes for addressing, if you want to develop programs compatible to the IndraLogic L20.

The memory organization of the IndraControl L20 allows only one memory alignment for the declaration of I/O addresses on the basis of the used data types. I/O addresses must be assigned to start addresses having the same data capacity as the data type. The following table shows the factor for the start address to be considered for the respective data type:

Data type	Factor = Data capacity (bytes)
BYTE	1
WORD	2
DWORD	4

Fig. 4-27:   Factor for start addresses for the IndraControl L20

Example   When a byte is addressed, a DWORD-type I/O address may only be aligned with positions being divisible by 4:

```
Out01  AT %QB0 : DWORD;
```
```
Out02  AT %QB4 : DWORD;
```

The following declaration is not allowed:

```
Out03  AT %QB7 : DWORD;
```

The alignment with %QB7 is not allowed, as this I/O address is not divisible by 4. The compiler indicates an error.

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4.5 Download and Commissioning

Loading Configurations and PLC Program into the Control

Verify to Exclude Errors After finishing the programming the project can be verified in IndraLogic with menu function "Project, Rebuild all".

Download and Online Mode With menu function "Online, Log-in" the communication between programming system and the IndraLogic VPP 21 is started, and a change to the online mode occurs. If the current project was not compiled after opening it or after the last modification, it is compiled now (as for "Project, Compile"). If errors occur during the compilation, IndraLogic does not change to the online mode.

If the current project was modified after the last download on the control, but not closed, and if the last download information was not deleted with command "Project, Clear all", a dialog with the following request is opened:

"The program has been changed. Load changes? (Online Change)"

By answering <Yes> you confirm during logging-in, that the changed parts of the project are to be loaded into the control. With <Load all> the complete project is reloaded into the control. With <No> a logging-in occurs, but the changes made after the last download are not loaded into the control.

For this, refer also to the "Online Functions" in the IndraLogic documentation or help /2/.

Online Functions

With IndraLogic information about the status of the control can be retrieved with the help of the "Online Functions", see IndraLogic documentation or help /2/.

5   Additional Functions

5.1   Firmware Management

Firmware downloads can be only executed, if the control is in the stop status.
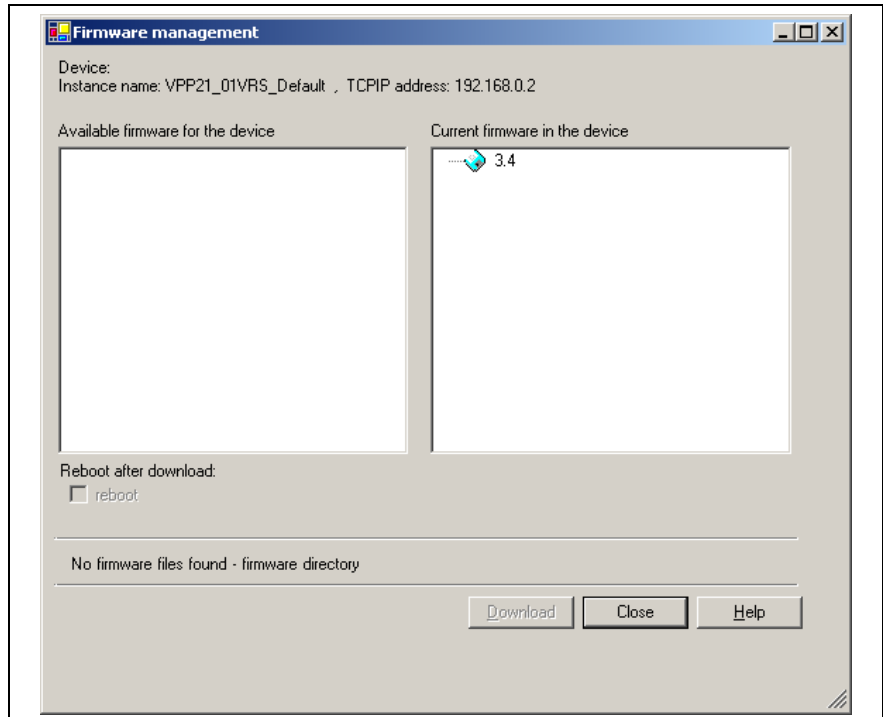
Fig. 5-1:   Example for the dialog "Firmware management"

For further information refer to the documentation or online help of IndraWorks /5/.

5.2   Importing IndraLogic Project File

Via the context menu of the device an existing IndraLogic project can be imported. Thus, projects can be edited in IndraWorks, that have been created with IndraLogic stand-alone (version without IndraWorks) or with CoDeSys. You can also import projects created within IndraWorks.
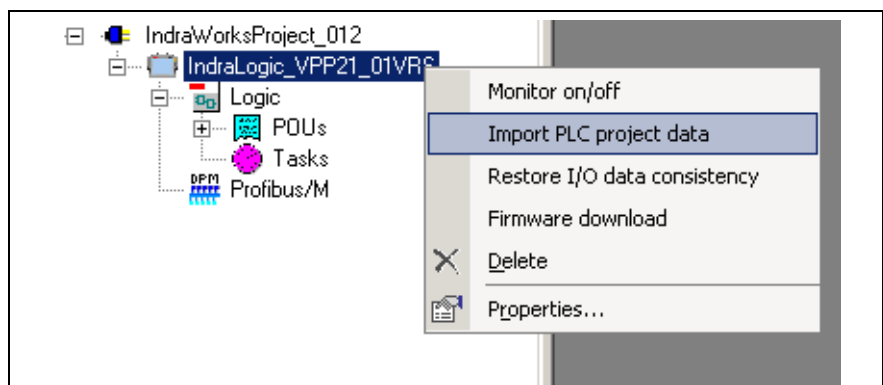
Fig. 5-2:   Context menu, device

For further information refer to the documentation or online help of IndraWorks /5/.

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5.3   IndraLogic Functions

If IndraLogic is started, the context menu changes. Now, it is possible to

- compile the IndraLogic project (Translate all)
- shut down IndraLogic
- log-in or log-out the control
- save project files with a new name
- update all blocks created in IndraLogic as well as modifications of configuration settings in the IndraWorks project explorer.
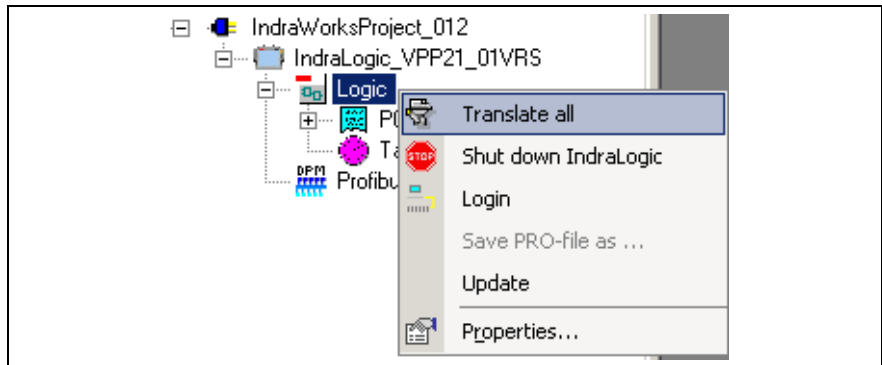
Fig. 5-3:   IndraLogic project: Context menu, if IndraLogic is started

5.4   Further Settings

Further settings, like

- saving IndraLogic settings
- offline operation
- generating and sending symbol file
- replacing constants
- address verification
- automatic loading of the boot project

can be made in the "Further settings" tab. This tab can be called up via context menu "Properties", if IndraLogic is not started.
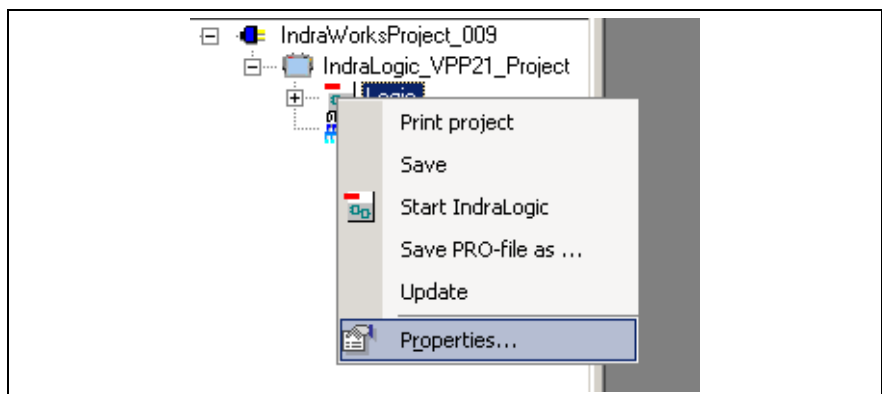
Fig. 5-4:   IndraLogic project: Further settings

For further information refer to the documentation or online help of IndraWorks /5/.

6 Libraries

6.1 Overview

The following table contains all general libraries as well as the libraries especially provided for the IndraLogic VPP 21.

To link libraries with the current project, please consider under "PLC Programming with IndraLogic" section "PLC Programming with IndraLogic".

| Name of the library	Function	See
AnalyzationNew	Blocks to analyze expressions	/2/
BusDiag	Diagnostic information of the Hilscher DP bus master	In this chapter
HMI_MKeys	M key functionalities with IndraWorks HMI	/5/
Iecsfc	– Internal use –	–
IL_VCP_DP	Coupling the Rexroth small operator terminals "VCP" with Profibus DP connection to the PLC	In this chapter
MP_PLCopen	MotionControl blocks	/7/
NetVarUdp_LIB_V23	Library with blocks for the application of network variables and the parameter manager, i. e. for data exchange between two or more controls	Networkfunctionality.pdf
PLCOpenFieldBus	MotionControl on the basis of the PLCOpen	/7/
RIL_Check	Automatic monitoring of over-ranges	In this chapter
RIL_CommonTypes	– Internal use –	–
RIL_ProfibusDP	Profibus-DPV1 services, diagnostic interface between Profibus master and PLC program, sync and freeze	In this chapter
RIL_Utilities	General IL functions and function blocks	In this chapter
Default	Default FBs and functions of the IEC 61131-3	/2/
SysLibDPV1Hilscher	Profibus DPV1 services of the Hilscher DP bus master	In this chapter
SysLibFileAsync	Asynchronous file accesses from the IEC application	SysLibFileAsync.pdf
SysLibFile	File system support on the IndraLogic VPP 21	SysLibFile.pdf
SysLibSockets	Access to sockets for the communication via TCP/IP and UDP	SysLibSockets.pdf
SysLibTime	Retrieve real-time clock of the IndraLogic VPP 21	SysLibTime.pdf
Util	As supplement to the Default.lib Blocks for BCD converting, bit/byte functions, mathematic help functions, controllers, signal generators, function manipulators and analog value processing	/2/

Fig. 6-1: Overview of IndraLogic VPP 21 libraries

Note: Libraries for internal use are automatically loaded as soon as they are referenced. Therefore, they must not be inserted in the library manager.

Concerning the system and firmware libraries please also consider the online help of IndraLogic. The documentation about the system libraries (SysLibXXX.pdf) you will find in a sub-directory of IndraLogic, e. g.:

C:/Program Files/Rexroth/IndraWorks/IndraLogic/Documents/English

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6.2   **BusDiag**

This library allows to read the specific diagnostic information of the Hilscher DP bus master.

Note: We recommend to use the more comprehensive library RIL_ProfibusDP.lib instead of the BusDiag.lib.

You will find further information on the BusDiag.lib in the description of the Hilscher bus card.

6.3 IL_VCP_DP

Overview

With this library the small operator terminals "VCP" of Rexroth with Profibus DP connection are coupled to the PLC. For this, three function blocks can be alternatively used:

- VCP_PBS16_A4096
- VCP_PBS32_A4096
- VCP_PBS32_A65536

VCP_PBS16_A4096

This function block (FB) activates the Profibus DP protocol for the small operator terminals VCPxx. Additionally, the I/O image of the physical addresses between PLC and operator terminal is generated.

The data capacity of the data transmission is 16 bytes. The size of the address area available via an ARRAY is 4096 bytes (inputs and outputs included).

Fig. 6-2:   VCP_PBS16_A4096

	Name	**Type**	**Comment**
VAR_INPUT	Enable	BOOL	TRUE: FB is executed FALSE: FB is not executed
	Reset_Error	BOOL	TRUE: Reset "Error" (to FALSE) and "ErrorNo" is set to 0.
VAR_IN_OUT	Data_in	ARRAY [0..15] OF BYTE	Data to connect the physical inputs of the small operator terminal
	Data_out	ARRAY [0..15] OF BYTE	Data to connect the physical outputs of the small operator terminal
	TVar	ARRAY [0..4095] OF BYTE	Array to read from and write to the operator terminal.
VAR_OUTPUT	Active	BOOL	TRUE as long as "Enable" is also TRUE
	Error	BOOL	TRUE when an error occurs. Can be reset with "Reset-Error".
	ErrorNo	USINT	Error type: 2: InputRangeError 4: Calculation error

Fig. 6-3:   Interface of VCP_PBS16_A4096

VI Composer   During the configuration with the Rexroth VI Composer the addresses of the variable list refer to the respective byte in array "TVar", that is used in the PLC program to exchange data.

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Error Handling

As soon as an error occurs, the communication is interrupted and the display of the small operator terminal indicates "COMMUNICATION ERROR, ERROR CODE 110".

The error type (ErrorNo) shows, if there's an error in the address calculation (CalculationError), or if the selected data capacity for Data_in or Data_out is too high (InputRangeError).

VCP_PBS32_A4096

This function block (FB) activates the Profibus DP protocol for the small operator terminals VCPxx. Additionally, the I/O image of the physical addresses between PLC and operator terminal is generated.

The data capacity of the data transmission is 32 bytes. The size of the address area available via an ARRAY is 4096 bytes (inputs and outputs included).
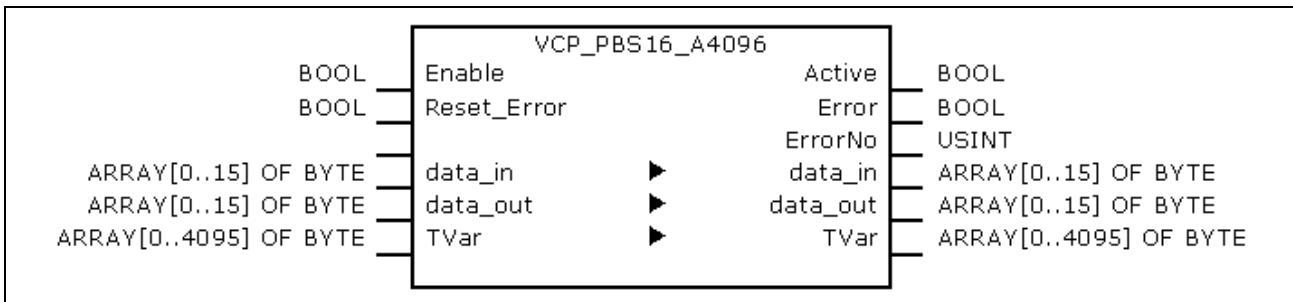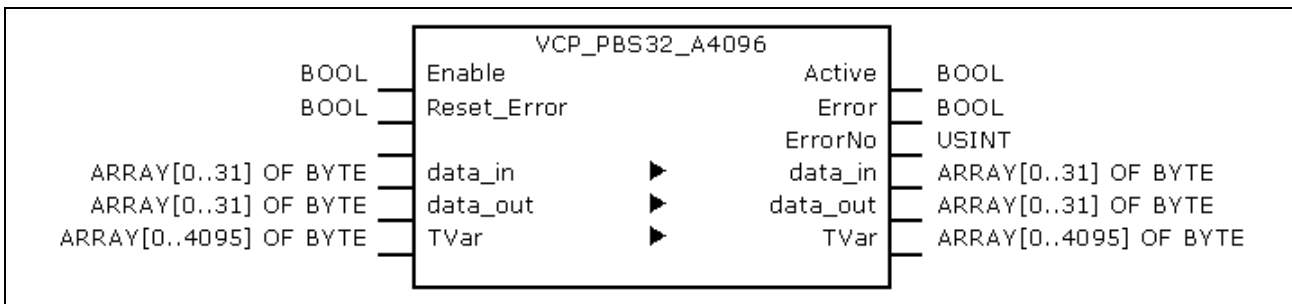

Fig. 6-4:   VCP_PBS32_A4096

	Name	**Type**	**Comment**
VAR_INPUT	Enable	BOOL	TRUE: FB is executed FALSE: FB is not executed
	Reset_Error	BOOL	TRUE: Reset "Error" (to FALSE) and "ErrorNo" is set to 0.
VAR_IN_OUT	Data_in	ARRAY [0..31] OF BYTE	Data to connect the physical inputs of the small operator terminal
	Data_out	ARRAY [0..31] OF BYTE	Data to connect the physical outputs of the small operator terminal
	TVar	ARRAY [0..4095] OF BYTE	Array to read from and write to the operator terminal.
VAR_OUTPUT	Active	BOOL	TRUE as long as "Enable" is also TRUE
	Error	BOOL	TRUE when an error occurs. Can be reset with "Reset-Error".
	ErrorNo	USINT	Error type: 4: Calculation error

Fig. 6-5:   Interface of VCP_PBS32_A4096

VI Composer

During the configuration with the Rexroth VI Composer the addresses of the variable list refer to the respective byte in array "TVar", that is used in the PLC program to exchange data.

Error Handling

As soon as an error occurs, the communication is interrupted and the display of the small operator terminal indicates "COMMUNICATION ERROR, ERROR CODE 110".

The error type (ErrorNo) indicates that the error is an address calculation error (CalculationError).

VCP_PBS32_A65536

This function block (FB) activates the Profibus DP protocol for the small operator terminals VCPxx. Additionally, the I/O image of the physical addresses between PLC and operator terminal is generated.

The data capacity of the data transmission is 32 bytes. The size of the address area available via an ARRAY is 65536 bytes (inputs and outputs included).
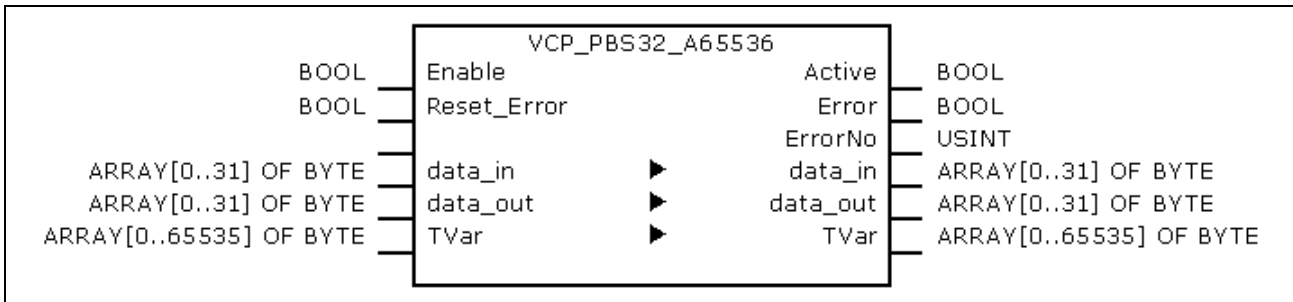
```
                           VCP_PBS32_A65536
BOOL __ Enable                          Active __ BOOL
BOOL __ Reset_Error                      Error __ BOOL
                                        ErrorNo __ USINT
ARRAY[0..31] OF BYTE __ data_in    ▶    data_in __ ARRAY[0..31] OF BYTE
ARRAY[0..31] OF BYTE __ data_out   ▶    data_out __ ARRAY[0..31] OF BYTE
ARRAY[0..65535] OF BYTE __ TVar    ▶        TVar __ ARRAY[0..65535] OF BYTE
```

Fig. 6-6:   VCP_PBS32_A65536

	Name	Type	Comment
VAR_INPUT	Enable	BOOL	TRUE: FB is executed FALSE: FB is not executed
	Reset_Error	BOOL	TRUE: Reset "Error" (to FALSE) and "ErrorNo" is set to 0.
VAR_IN_OUT	Data_in	ARRAY [0..31] OF BYTE	Data to connect the physical inputs of the small operator terminal
	Data_out	ARRAY [0..31] OF BYTE	Data to connect the physical outputs of the small operator terminal
	TVar	ARRAY [0..65535] OF BYTE	Array to read from and write to the operator terminal.
VAR_OUTPUT	Active	BOOL	TRUE as long as "Enable" is also TRUE
	Error	BOOL	TRUE when an error occurs. Can be reset with "Reset-Error".
	ErrorNo	USINT	Error type: 4: Calculation error

Fig. 6-7:   Interface of VCP_PBS32_A65536

VI Composer   During the configuration with the Rexroth VI Composer the addresses of the variable list refer to the respective byte in array "TVar", that is used in the PLC program to exchange data.

Error Handling   As soon as an error occurs, the communication is interrupted and the display of the small operator terminal indicates "COMMUNICATION ERROR, ERROR CODE 110".

The error type (ErrorNo) indicates that the error is an address calculation error (CalculationError).

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6.4   RIL_Check

Faulty accesses (accidentally) programmed outside of the ranges of arrays and subrange types of variables, as well as the division by zero, are not compensated by the IndraLogic compiler and/or the runtime system and cause partly unpredictable errors during program processing. If you insert library RIL_Check.lib such over-ranges are monitored and prevented. Thereby, the access for arrays and subrange system types are limited to the smallest or highest possible value. Thus, e. g. concerning an array, the element with the highest indices is accessed, even if a higher index value was specified in the PLC program. For a division by zero the divisor is replaced by "1".

Note:	If the RIL_Check.lib library is integrated in the PLC project, before each testable operation the corresponding test function is automatically inserted (invisible for the user). Further function calls are not necessary!

Note:	If library RIL_Check.lib is integrated in the PLC project, the PLC cycle time is charged, as each testable operation is automatically monitored. With respect to the robustness of a PLC project and the safety of the whole system we recommend to use the RIL_Check.lib in the PLC project. When using the MP_PLCOpen.lib library, the RIL_Check.lib is required. In this case the RIL_Check.lib must be integrated in the PLC project.

Functions   All functions contained in the RIL_Check (see Fig. 6-8) are automatically integrated in the PLC program and must not be explicitly called.

Designation	Description
CheckBounds	Automatic verification, if the permissible indices of the access to array elements is exceeded or fallen below the minimum value.
CheckDivByte	Automatic verification on division by zero (BYTE access).
CheckDivDWord	Automatic verification on division by zero (DWORD access).
CheckDivReal	Automatic verification on division by zero (REAL access).
CheckDivWord	Automatic verification on division by zero (WORD access).
CheckRangeSigned	Automatic verification, if the permissible value range of a signed variable is exceeded or fallen below the minimum value.
CheckRangeUnsigned	Automatic verification, if the permissible value range of an unsigned variable is exceeded or fallen below the minimum value.

Fig. 6-8:   Funktions of RIL_Check

CheckExceedingOccurred   You can exactly determine the error cause by directed requesting of the bits in the global variable „CheckExceedingOccurred". All error accesses are prevented by RIL_Check, so that the permissible value range is not exceeded or fallen below the minimum value and that no division by zero occurs. The single bits have the following meaning:

Bit variable	Value	Meaning
CheckExceedingOccurred.0	16#01	CheckBoundsLowerLimitation: The permissible indices of the access to array elements are fallen below the minimum value.
CheckExceedingOccurred.1	16#02	CheckBoundsUpperLimitation: The permissible indices of the access to array elements are exceeded.
CheckExceedingOccurred.2	16#04	CheckBoundsExceedingLimitation: The permissible indices of the access to array elements are exceeded or fallen below the minimum value.
CheckExceedingOccurred.3	16#08	CheckRangeLowerLimitation: The permissible value range of a variable is fallen below the minimum value.
CheckExceedingOccurred.4	16#16	CheckRangeUpperLimitation: The permissible value range of a variable is exceeded.
CheckExceedingOccurred.5	16#32	CheckRangeExceedingLimitation: The permissible value range of a variable is exceeded or fallen below the minimum value.
CheckExceedingOccurred.6	16#64	DivisionByZeroPrevention: Division by zero.

Fig. 6-9:   CheckExceedingOccurred

Sample Program   The following PLC sample program shows the use of the variable CheckExceedingOccurred. The limitation of arrays with CheckBounds, always sets the respective bit in error case, when the permissible value range is exceeded or fallen below the minimum value (CheckBoundsLowerLimitation or CheckBoundsUpperLimitation) and the general bit of the access violation (CheckBoundsExceedingLimitation). Thus, a general or detailed verification, if a limit value was exceeded, can be realized.

```
CheckExceedingOccurred := 16#00;        (* Resetting the variable *)


IF Axis_Data[AxisNo].bCheckAccessOK     (* Array access *)
THEN
...


IF CheckExceedingOccurred.2 (* Array access violation detected? *)
THEN
        IF CheckExceedingOccurred.0 (* Bit set, if value below specified range? *)
        THEN
                String := 'Access below the possible array range'
                ...


        END_IF
        IF CheckExceedingOccurred.0 (* Bit set, if value above specified range? *)
        THEN
                String := 'Access above the possible array range'
                ...


        END_IF
ELSE
  String := 'Access successful'
END_IF
```

Fig. 6-10: Sample program: over-range for arrays

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6.5   RIL_ProfibusDP

Overview

When using this library, not only DPV1 services of the Profibus master (DP master class 1) are provided, but also a diagnostic interface between Profibus master and PLC program is created.

DPV1 Services

Function Blocks   The function blocks serve for reading and writing access for the acyclic data exchange (DPV1):

- DP_RDREC
- DP_WRREC

Functions   Moreover, help functions for addressing are available:

- DP_ADDR
- DP_ID
- DP_SLOT

Diagnostic Information

Diagnostic information can be determined via function blocks. The diagnosis differs in

- Slave Diagnostic Data According to the Profibus DP Standard: "DP_RDIAG" and "DP_RDIAG_EXT"
- General Field Bus Diagnosis: "fbd..."

Data Types   Some of these data are administrated in special data types (arrays, structures):

- tFBD_BM_INFO
- tFBD_BIT_LIST
- tFBD_KSD_LIST

Function Blocks
- DP_RDIAG
- DP_RDIAG_EXT
- fbdBaudrateGet
- fbdBmErrorGet
- fbdBmInfoGet
- fbdBmStateGet
- fbdKsdListGet
- fbdPdTypeGet
- fbdPrjSlaveListGet
- fbdSlaveDiagListGet

Functions   Moreover, help functions for addressing are available:

- DP_ADDR
- DP_ID
- DP_SLOT

Slave Diagnostic Data According to the Profibus DP Standard

Profibus-specific diagnostic information according to the Profibus DP standard can be read via the following function blocks:

- DP_RDIAG
- DP_RDIAG_EXT

The slave diagnostic data are available with the parameters DINFO or DINFO_PTR. While for "DINFO" all diagnostic data are archived in an array, "DINFO_PTR" is a pointer to the diagnostic data.

The slave diagnostic data are subdivided into two parts:

- general part with a fixed length of 6 bytes
- extended diagnosis (slave-specific, with variable length)

Offset	Type	Designation	Description
0	BYTE	Station status_1	See below
1	BYTE	Station status_2	See below
2	BYTE	Station status_3	See below
3	BYTE	Master_Add	Bus address of the master having parameterized the slave
4	WORD	Ident_Number	Ident number of the slave
6 – 243		Ext_Diag_Data	Extended slave diagnosis according to Profibus DP standard

Fig. 6-11:   Slave diagnostic data

The following description of the station status 1 to 3 is an extract from the Profibus DP standard.

Bit	Designation	Description
7	Master_Lock	The DP slave was parameterized by another master. This bit is set by the DP master (class 1), if the address in octet 4 is not equal to 255 and not equal to the own address. The DP slave sets this bit permanently to zero.
6	Prm_Fault	This bit is set by the DP slave, if the last parameter telegram was faulty, e. g., wrong length, wrong Ident_Number, invalid parameters.
5	Invalid_Slave_Response	This bit is set by the DP master, as soon as one of the addressed DP slaves receives an implausible response. The DP slave sets this bit permanently to zero.
4	Not_Supported	This bit is set by the DP slave, as soon as a function was requested, that is not supported by this DP slave.
3	Ext_Diag	This bit is set by the DP slave. If the bit is set, a diagnostic entry must be available in the slave-specific diagnostic area (Ext_Diag_Data). If the bit is not set, a status message might be present in the slave-specific diagnostic area (Ext_Diag_Data). The meaning of this status message must be defined according to the respective application.
2	Cfg_Fault	This bit is set by the DP slave, as soon as the configuration data lastly received by the DP master do not correspond to the data determined by the DP slave.
1	Station_Not_Ready	This bit is set by the DP slave, if the DP slave is not yet ready for data exchange.
0	Station_Non_Existent	This bit is set by the DP master, if this DP slave can not be reached via the bus. If this bit is set, the diagnostic bits contain the status of the last diagnostic message or the initial value. The DP slave sets this bit permanently to zero.

Fig. 6-12:   Station status_1

Bit	Designation	Description
7	Deactivated	This bit is set by the DP master, as soon as the DP slave in the DP slave parameter set is not indicated as active and was removed from the cyclic processing. The DP slave sets this bit permanently to zero.
6	Reserved	-
5	Sync_Mode	This bit is set by the DP slave, as soon as it received the sync control command.
4	Freeze_Mode	This bit is set by the DP slave, as soon as it received the freeze control command.
3	WD_On (Watchdog)	This bit is set by the DP slave, as soon as its response monitoring is activated.
2	1	The DP slave sets this bit permanently to zero.
1	Stat_Diag (static diagnosis)	If the DP slave sets this bit, the DP master has to retrieve diagnostic information as long as this bit is deleted again. The DP slave sets this bit, for example in the case, if it can't provide any valid user data.
0	Prm_Req	If the DP slave sets this bit, it must be re-parameterized and re-configured. The bit remains set, as long as a parameterization occurred. This bit is set by the DP slave.

Fig. 6-13:   Station status_2

Bit	Designation	Description
7	Ext_Diag_Overflow	If this bit is set, there're more diagnostic information as specified in Ext_Diag_Data. The DP slave sets this bit, for example, if there're more channel diagnoses than the DP slave can enter in its transmitter buffer; or the DP master sets this bit, if the DP slave sends more diagnostic information than the DP master is able to enter in its diagnostic buffer.
6	Reserved	-
5	Reserved	-
4	Reserved	-
3	Reserved	-
2	Reserved	-
1	Reserved	-
0	Reserved	-

Fig. 6-14:   Station status_3

You will find further information on the diagnostic functions in the description of the function blocks.

General Field Bus Diagnosis

The general field bus diagnosis provides the following data areas:

- BmState: Bus master status word, see "tFBD_BM_INFO"
- BmError: Bus master error word, see "tFBD_BM_INFO"
- SD: Slave diagnostic list, see "tFBD_BIT_LIST"
- KSD: Classified slave diagnosis, see "tFBD_KSD_LIST"
- Projected slave list, see "tFBD_BIT_LIST"

Bus Master Status Word   "BmState" provides an overview of the status of the bus master and the slaves at the field bus. Here, you can recognize for example, if at least for one slave a diagnosis is applied.

Bus Master Error Word   In "BmError" fatal errors rendering the operation at the field bus impossible are indicated.

Slave Diagnostic List   SD indicates which slaves signal diagnosis.

Classified Slave Diagnosis   KSD provides detailed information. It indicates, which slaves signal diagnosis and divides the diagnosis into error classes.

Projected Slave List   The projected slave list contains all available slaves according to the master configuration file. For example, with this list projected slaves can be compared with the slaves currently available at the field bus.

You will find further information on the data areas in the description of the Data Types and on the diagnostic functions in the description of the function blocks.

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Data Types

tFBD_BM_INFO

This structure combines the variables "PdType", "BmStatus" and "BmError". It is used in function block "fbdBmInfoGet".

```
0001 TYPE tFBD_BM_INFO :
0002 STRUCT
0003     PdType : INT;
0004     BmState : WORD;
0005     BmError : WORD;
0006 END_STRUCT
0007 END_TYPE
```

Fig. 6-15:   tFBD_BM_INFO

PdType: Peripheral Driver Function block "fbdBmInfoGet" determines the type of the installed peripheral driver and indicates it in "PdType":

Driver	Description
FBD_PDT_NONE	No peripheral driver installed
FBD_PDT_PCI_BMDP	Peripheral driver: Profibus DP
FBD_PDT_PCI_BMCAN	Peripheral driver: CAN Open (at present, not available)
FBD_PDT_PCI_BMIBS	Peripheral driver: Interbus (at present, not available)

Fig. 6-16:   Installed peripheral driver in "PdType"

BmState: Bus Master Status Word The bus master status word "BmState" provides an overview of the status of the bus master and the slaves at the field bus. Here, you can recognize for example, if at least for one slave a diagnosis is applied. Each set bit (TRUE) in "BmState" represents a status:

Bit	Status	Description
0	BMS_BMF	Bus master error: This bit indicates, that there's a bus master error. In this case, the bus master error word contains more detailed information
1	BMS_KSD	Classified slave diagnosis: If this bit is set, at least one slave indicates a classified diagnosis. Which classified diagnosis/diagnoses is/are set, can be determined by the bits 8 to 13.
2	BMS_SD	Slave diagnosis: If this bit is set, at least one slave indicates a slave diagnosis.
3	-	- Reserved -
4	-	- Reserved -
5	-	- Reserved -
6	-	- Reserved -
7	BMS_AKTIV	Active identification: This bit must always have value 1. If this is not the case, there's a fatal error in the software of the bus master.

Bit	Status	Description
8	BMS_SNE	One or several slaves are not accessible via the bus
9	BMS_SKF	One or several slaves indicate configuration errors
10	BMS_DPS	One or several slaves indicate static diagnosis
11	BMS_EXD	One or several slaves indicate extended diagnosis
12	BMS_SNB	One or several slaves are not ready for the cyclic data exchange
13	BMS_SF	One or several slaves indicate another error
14	-	- Reserved -
15	-	- Reserved -

Fig. 6-17:   Status coding in "BmState"

BmState is used in the following function blocks:

- fbdBmInfoGet
- fbdBmStateGet

BmError: Bus Master Error Word   In the bus master error word "BmError" fatal errors rendering the operation at the field bus impossible are indicated. Each set bit (TRUE) in "BmError" represents an error:

Bit	Error	Description
0	BMF_HW_ERR	Hardware error
1	BMF_MPS_ERR	Master parameter set (field bus configuration file) is missing or faulty
2	BMF_BUS_ERR	Error at the field bus (e. g. short-circuit, ...)
3	BMF_SW_ERR	System error in the peripheral driver (i. e. the driver software has detected a fatal error)

*   "BMF_OK" indicates, that no error occurred

Fig. 6-18:   Error coding in "BmError"

BmError is used in the following function blocks:

- fbdBmErrorGet
- fbdBmInfoGet

tFBD_BIT_LIST

The bit list "tFBD_BIT_LIST" has a defined length of 16 bytes (128 bits).

```
0001 TYPE tFBD_BIT_LIST :
0002     ARRAY [0..15] OF BYTE;
0003 END_TYPE
```

Fig. 6-19:   tFBD_BIT_LIST

Each bit of the bit list is assigned to a bus address of the slave (Profibus: FDL address). Thus, e. g. the lowest-order bit in the first array element (ARRAY[0]) is assigned to the Profibus device with address 0:
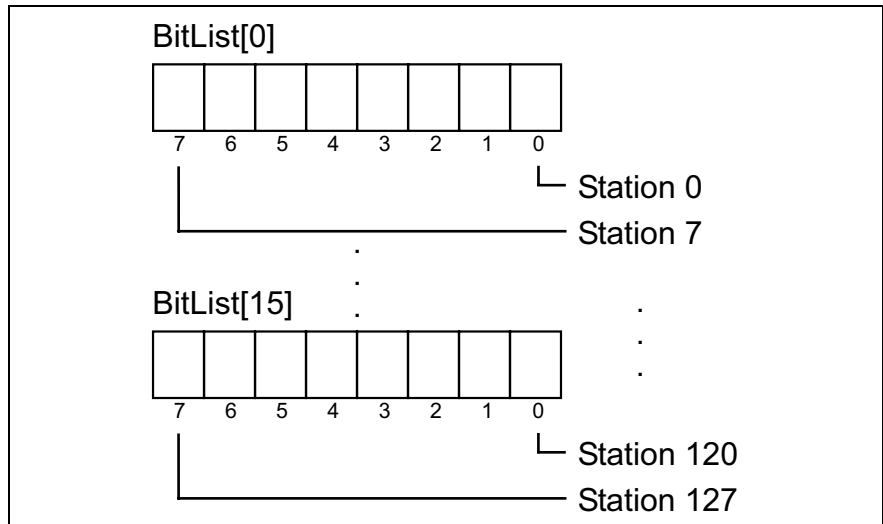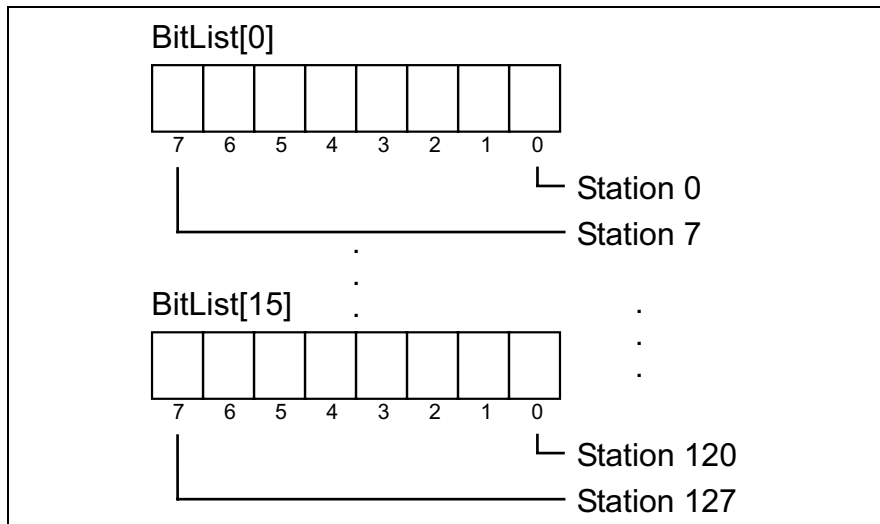

Fig. 6-20:   Coding of the bit list

The bit list is used in the following function block:

- fbdPrjSlaveListGet
- fbdSlaveDiagListGet

Additionally, the bit list is used in the tFBD_KSD_LIST (classified slave diagnosis).

tFBD_KSD_LIST

The list of the classified slave diagnosis (KSD list) consists of six bit lists. Thus, a bit list exists for each error type.

```
0001 TYPE tFBD_KSD_LIST :
0002     STRUCT
0003         SNE : tFBD_BIT_LIST;
0004         SKF : tFBD_BIT_LIST;
0005         DPS : tFBD_BIT_LIST;
0006         EXD : tFBD_BIT_LIST;
0007         SNB : tFBD_BIT_LIST;
0008         SF  : tFBD_BIT_LIST;
0009     END_STRUCT
0010 END_TYPE
```

Fig. 6-21:   tFBD_KSD_LIST

Classified Slave Diagnosis (KSD)   The classified slave diagnosis distinguishes the following error types:

SNE	Slave not accessible. The slave is not accessible at the bus. Possible causes: – Slave not available – Voltage at the slave switched off – Faulty bus installation – Physical malfunctions
SKF	Slave configuration error. The slave type or the I/O configuration of the slave does not correspond to the projected values in the field bus configuration file of the master.
DPS	Slave indicates static diagnosis: The slave can't provide valid user data. The application layer of the slave is not ready for data exchange with the master.
EXD	Slave indicates extended diagnosis. The extended diagnosis is slave-specific and can be taken from the description of the slave. Possible causes: – Load voltage missing/switched off (e. g. in case of Emergency Stop) – Short-circuit at one output – Overload – Over-temperature – Line break
SNB	Slave is not ready. The slave is not ready for data exchange, as it is not yet put into operation by the master (message from the protocol layer of the slave).
SF	Slave indicates another error.

Fig. 6-22:   Classified slave diagnosis

Each bit of a bit list is assigned to a bus address of the slave (Profibus: FDL address). Thus, the lowest-order bit in the first array element (ARRAY[0]) is assigned to the Profibus device with address 0:

Fig. 6-23:   Coding of the bit list

Bit[x] = FALSE	Slave[x] has no diagnosis
Bit[x] = TRUE	Slave[x] has diagnosis

Fig. 6-24:   Bit list: Classified slave diagnosis

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DP_RDIAG

The diagnostic data of a slave are read from the DP master (DPM1) using function block DP_RDIAG. The data buffer of the diagnostic data must be provided to address it via a POINTER.
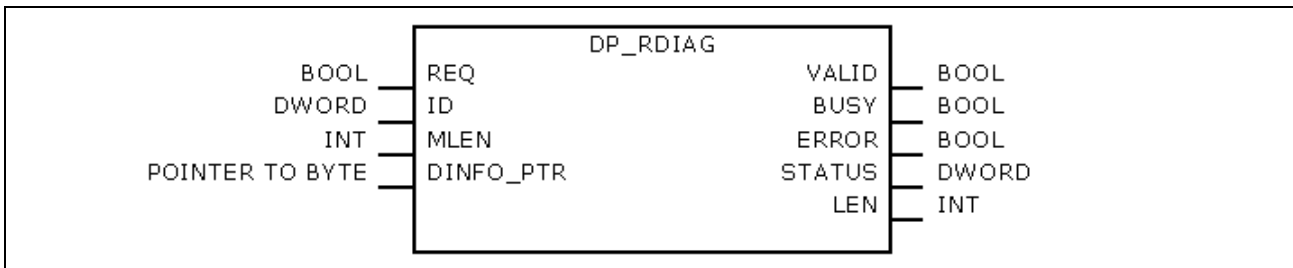
Fig. 6-25: DP_RDIAG

	Name	Type	Comment
VAR_INPUT	REQ	BOOL	TRUE: Start reception
	ID	DWORD	Slot handle, see the following table
	MLEN	INT	Maximum length of the data to be read
	DINFO_PTR	POINTER TO BYTE	Pointer to the data buffer of the Slave Diagnostic Data According to the Profibus DP Standard
VAR_OUTPUT	VALID	BOOL	TRUE: New, valid diagnostic data available
	ERROR	BOOL	TRUE: Error/s occurred
	BUSY	BOOL	TRUE: The function block is busy. As long as BUSY = TRUE, the data can not yet be evaluated.
	STATUS	DWORD	Lastly defined status
	LEN	INT	Length of the diagnostic data in bytes

Fig. 6-26: Interface of DP_RDIAG

Bytes	Contents	Description
0	MASTER	ID of the DP system: Has permanently value 0, as the IndraLogic VPP 21 contains exactly one DP master.
1	SEGMENT	Number of the DP segment
2	STATION	Number of the DP slave (bus address).
3	SLOT	Number of the slot within the slave

Fig. 6-27: Slot handle: Parameter "ID"

Example: To address the slave with bus address 12, the ID has value 16#000C0000.

Function DP_ID serves for creating the ID from the individual components.

DP_RDIAG_EXT

The diagnostic data of a slave are read from the DP master (DPM1) using function block DP_RDIAG_EXT. The diagnostic data are stored in an ARRAY.
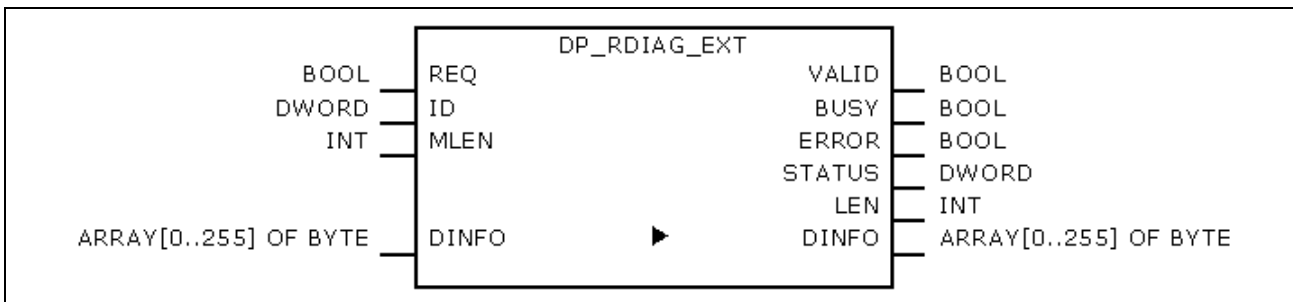
Fig. 6-28:   DP_RDIAG_EXT

	Name	Type	Comment
VAR_INPUT	REQ	BOOL	TRUE: Start reception
	ID	DWORD	Slot handle, see the following table
	MLEN	INT	Maximum length of the data to be read
VAR_IN_OUT	DINFO	ARRAY [0..255] OF BYTE	Slave Diagnostic Data According to the Profibus DP Standard
VAR_OUTPUT	VALID	BOOL	TRUE: New, valid diagnostic data available
	ERROR	BOOL	TRUE: Error/s occurred
	BUSY	BOOL	TRUE: The function block is busy. As long as BUSY = TRUE, the data can not yet be evaluated.
	STATUS	DWORD	Lastly defined status
	LEN	INT	Length of the diagnostic data in bytes

Fig. 6-29:   Interface of DP_RDIAG_EXT

Bytes	Contents	Description
0	MASTER	ID of the DP system: Has permanently value 0, as the IndraLogic VPP 21 contains exactly one DP master.
1	SEGMENT	Number of the DP segment
2	STATION	Number of the DP slave (bus address).
3	SLOT	Number of the slot within the slave

Fig. 6-30:   Slot handle: Parameter "ID"

Example: To address the slave with bus address 12, the ID has value 16#000C0000.

Function DP_ID serves for creating the ID from the individual components.

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DP_RDREC

Function block DP_RDREC serves for reading access for the acyclic data exchange (DPV1). For the process data to be read a target area must be defined via a pointer addressing (POINTER).

```
                     DP_RDREC
    BOOL ___ REQ                    VALID ___ BOOL
   DWORD ___ ID                     ERROR ___ BOOL
     INT ___ INDEX                   BUSY ___ BOOL
   UDINT ___ MLEN                  STATUS ___ DWORD
POINTER TO BYTE ___ REC_PTR           LEN ___ UDINT
```
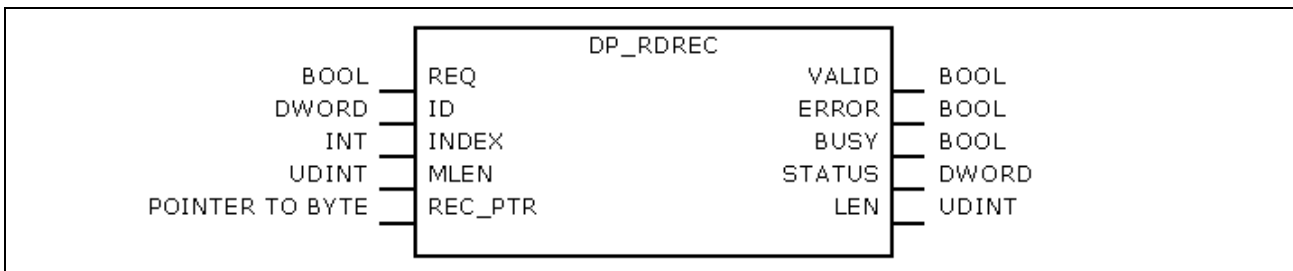
Fig. 6-31:   DP_RDREC

	Name	Type	Comment
VAR_INPUT	REQ	BOOL	TRUE: Start reading
	ID	DWORD	Slot handle, see the following table
	INDEX	INT	Index of the process data (offset)
	MLEN	UDINT	Maximum length of the process data in bytes
	REC_PTR	POINTER TO BYTE	Pointer to the target area
VAR_OUTPUT	VALID	BOOL	TRUE: New, valid data available
	ERROR	BOOL	TRUE: Error/s occurred
	BUSY	BOOL	TRUE: The function block is busy. As long as BUSY = TRUE, the data can not yet be evaluated.
	STATUS	DWORD	Lastly defined status
	LEN	UDINT	Length of the process data in bytes

Fig. 6-32:   Interface of DP_RDREC

Bytes	Contents	Description
0	MASTER	ID of the DP system: Has permanently value 0, as the IndraLogic VPP 21 contains exactly one DP master.
1	SEGMENT	Number of the DP segment
2	STATION	Number of the DP slave (bus address).
3	SLOT	Number of the slot within the slave

Fig. 6-33:   Slot handle: Parameter "ID"

Example: To address the slave with bus address 12, the ID has value 16#000C0000.

Function DP_ID serves for creating the ID from the individual components.

DP_WRREC

Function block DP_WRREC serves for reading access for the acyclic data exchange (DPV1). The process data to be written must provided via a pointer addressing (POINTER).

```
                        DP_WRREC
     BOOL __ REQ                    DONE __ BOOL
    DWORD __ ID                     BUSY __ BOOL
      INT __ INDEX                 ERROR __ BOOL
    UDINT __ LEN                  STATUS __ DWORD
POINTER TO BYTE __ REC_PTR           LEN __ UDINT
```
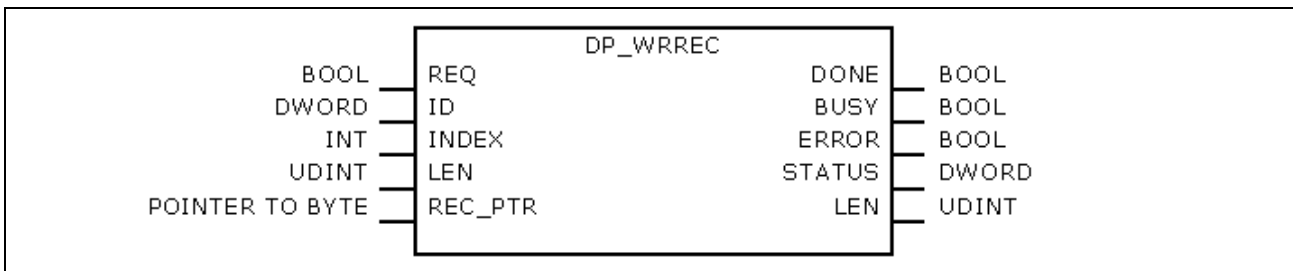
Fig. 6-34:   DP_WRREC

	Name	Type	Comment
VAR_INPUT	REQ	BOOL	TRUE: Start writing
	ID	DWORD	Slot handle, see the following table
	INDEX	INT	Index of the process data (offset)
	LEN	UDINT	Length of the process data in bytes
	REC_PTR	POINTER TO BYTE	Pointer to the process data to be written
VAR_OUTPUT	DONE	BOOL	TRUE: Call completed
	ERROR	BOOL	TRUE: Error/s occurred
	BUSY	BOOL	TRUE: The function block is busy. As long as BUSY = TRUE, the data can not yet be evaluated.
	STATUS	DWORD	Lastly defined status

Fig. 6-35:   Interface of DP_WRREC

Bytes	Contents	Description
0	MASTER	ID of the DP system: Has permanently value 0, as the IndraLogic VPP 21 contains exactly one DP master.
1	SEGMENT	Number of the DP segment
2	STATION	Number of the DP slave (bus address).
3	SLOT	Number of the slot within the slave

Fig. 6-36:   Slot handle: Parameter "ID"

Example: To address the slave with bus address 12, the ID has value 16#000C0000.

Function DP_ID serves for creating the ID from the individual components.

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fbdBaudrateGet

Function block fbdBaudrateGet reads the baud rate of the connected field bus. The baud rate is indicated in bits per second.

```
         fbdBaudrateGet
                    Baudrate ── UDINT
```
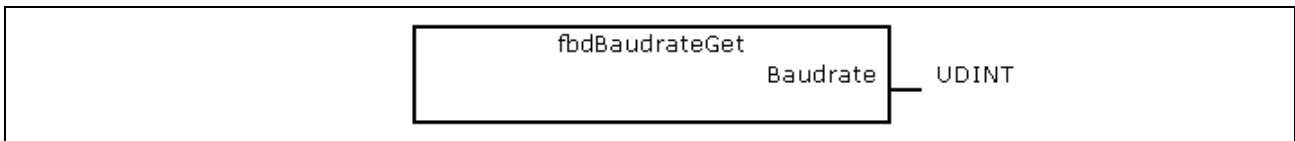
Fig. 6-37:   fbdBaudrateGet

	Name	Type	Comment
VAR_OUTPUT	Baud rate	UDINT	Baud rate at the field bus (bit/s)

Fig. 6-38:   Interface of fbdBaudrateGet

fbdBmErrorGet

Function block fbdBmErrorGet reads the current bus master error word.

```
         fbdBmErrorGet
                    BmError ── WORD
```
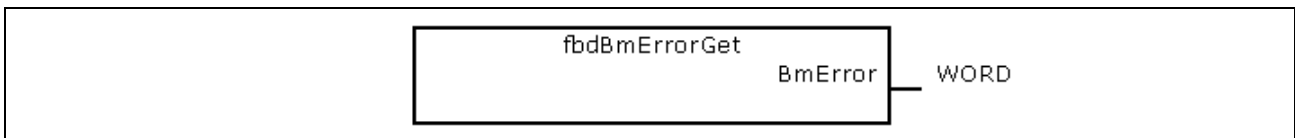
Fig. 6-39:   fbdBmErrorGet

	Name	Type	Comment
VAR_OUTPUT	BmError	WORD	See tFBD_BM_INFO

Fig. 6-40:   Interface of fbdBmErrorGet

fbdBmInfoGet

Function block fbdBmInfoGet provides the tFBD_BM_INFO structure. This structure contains PdType, BmStatus and BmError. Thus, the information is provided by one single call, instead of calling several differing functions.

```
         tfbdBmInfoGet
                    BmInfo ── tFBD_BM_INFO
```
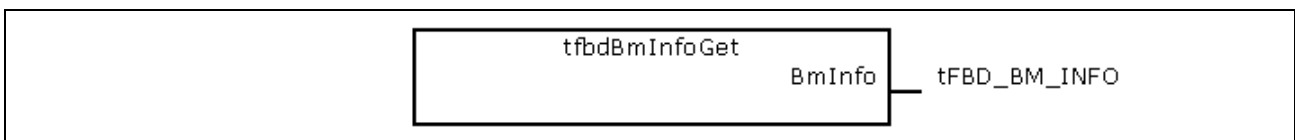
Fig. 6-41:   fbdBmInfoGet

	Name	Type	Comment
VAR_OUTPUT	BmInfo	tFBD_BM_INFO	See tFBD_BM_INFO

Fig. 6-42:   Interface of fbdBmInfoGet

fbdBmStateGet

Function block fbdBmStateGet reads the current bus master status word.

```
          fbdBmStateGet
                  BmState  ──  WORD
```
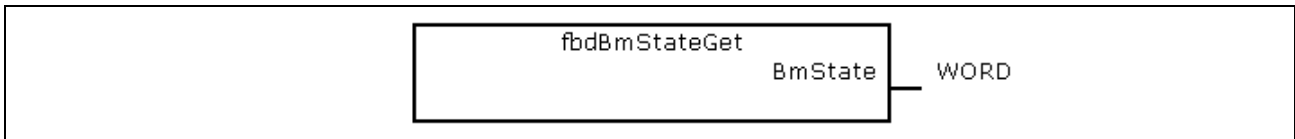
Fig. 6-43:   fbdBmStateGet

	Name	Type	Comment
VAR_OUTPUT	BmState	WORD	See tFBD_BM_INFO

Fig. 6-44:   Interface of fbdBmStateGet

fbdKsdListGet

Function block fbdKsdListGet reads the current KSD list.

```
          fbdKsdListGet
                  KsdList  ──  tFBD_KSD_LIST
```
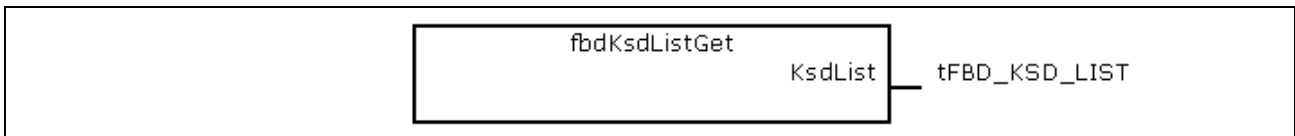
Fig. 6-45:   fbdKsdListGet

	Name	Type	Comment
VAR_OUTPUT	KsdList	tFBD_KSD_LIST	See tFBD_KSD_LIST

Fig. 6-46:   Interface of fbdKsdListGet

fbdPdTypeGet

Function block fbdPdTypeGet determines the type of the installed peripheral driver.

```
          fbdPdTypeGet
                  PdType  ──  INT
```
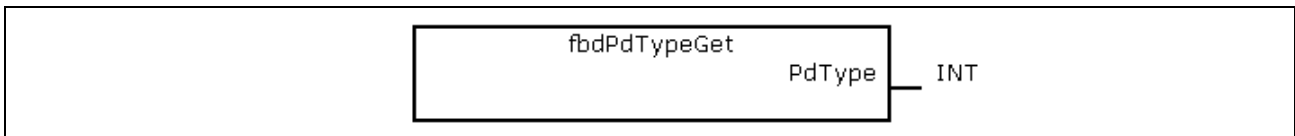
Fig. 6-47:   fbdPdTypeGet

	Name	Type	Comment
VAR_OUTPUT	PdType	INT	Peripheral driver type:
			PDT_NONE: No peripheral driver installed
			PDT_PCI_BMDP: PROFIBUS DP
			PDT_PCI_BMCAN: CAN Open
			PDT_PCI_BMIBS: INTERBUS S

Fig. 6-48:   Interface of fbdPdTypeGet

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fbdPrjSlaveListGet

Function block fbdPrjSlaveListGet reads the list of the projected slaves. The list contains all available slaves according to the master configuration file.

```
         fbdPrjSlaveListGet
                  PrjSlaveList  __  tFBDBIT_LIST
```
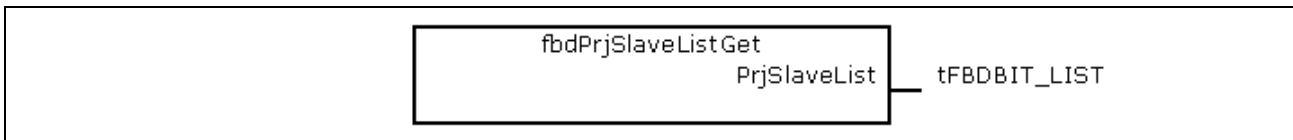
Fig. 6-49:   fbdPrjSlaveListGet

	Name	Type	Comment
VAR_OUTPUT	PrjSlaveList	tFBD_BIT_LIST	See tFBD_BIT_LIST

Fig. 6-50:   Interface of fbdPrjSlaveListGet

Each bit of the bit list is assigned to a bus address of the slave:

Bit[x] = TRUE	Slave[x] is projected
Bit[x] = FALSE	Slave[x] is not projected

Fig. 6-51:   Bit list: Projected slaves

fbdSlaveDiagListGet

Function block fbdSlaveDiagListGet reads the current slave diagnostic list.

```
         fbdSlaveDiagListGet
                  SlaveDiagList  __  tFBD_BIT_LIST
```
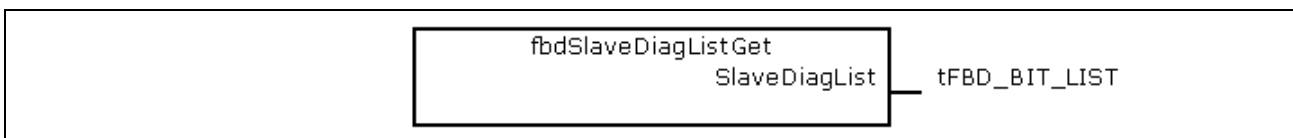
Fig. 6-52:   fbdSlaveDiagListGet

	Name	Type	Comment
VAR_OUTPUT	SlaveDiagList	tFBD_BIT_LIST	See tFBD_BIT_LIST

Fig. 6-53:   Interface of fbdSlaveDiagListGet

Each bit of the bit list is assigned to a bus address of the slave:

Bit[x] = TRUE	Slave[x] has diagnosis
Bit[x] = FALSE	Slave[x] has no diagnosis

Fig. 6-54:   Bit list: slave diagnosis

DP_SYCFR

The IndraLogic VPP 21 does not support any sync and freeze function of Profibus DP!

DP_ADDR

This function is not realized. This function can be called up as it is compatible to Profibus Guideline 2182, but it passes a handle unchanged.
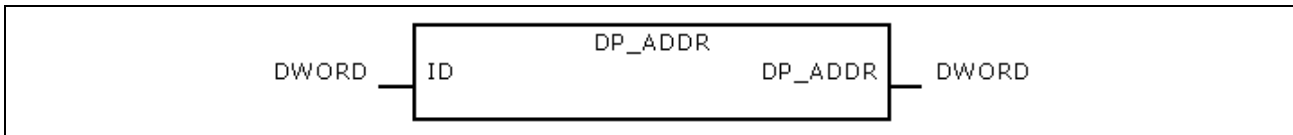
Fig. 6-55:   DP_ADDR

	Name	Type	Comment
VAR_INPUT	ID	DWORD	Slot handle
Function value		DWORD	

Fig. 6-56:   Interface of DP_ADDR

DP_ID

This function considers Profibus Guideline 2182. It provides the handle for a physical address of a slot.
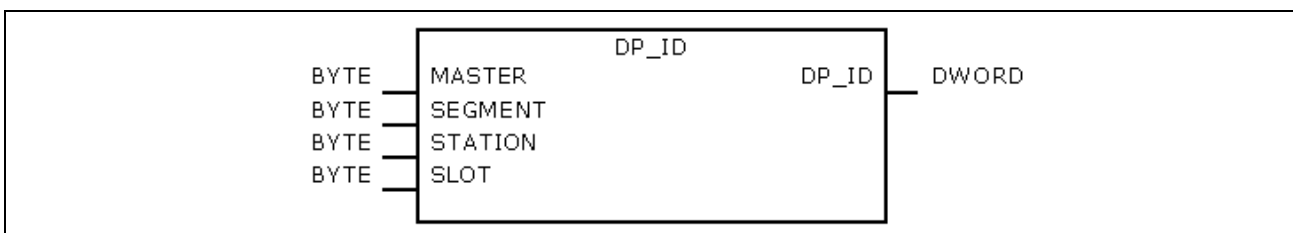
Fig. 6-57:   DP_ID

	Name	Type	Comment
VAR_INPUT	MASTER	BYTE	ID of the DP system: Has permanently value 0, as the IndraLogic VPP 21 contains exactly one DP master.
	SEGMENT	BYTE	Number of the DP segment
	STATION	BYTE	Number of the DP slave (bus address): If the command is to be valid for only one special slave, then the bus address of the slave must be entered here (0..125). Only for DP_SYCFR: However, if the command is to be entered for all slaves of a group, a global address (= 127) must be entered here.
	SLOT	BYTE	Number of the slot within the slave
Function value		DWORD	Slot handle

Fig. 6-58:   Interface of DP_ID

DP_SLOT

This function considers Profibus Guideline 2182. It sets the slot number defined in the slot handle.
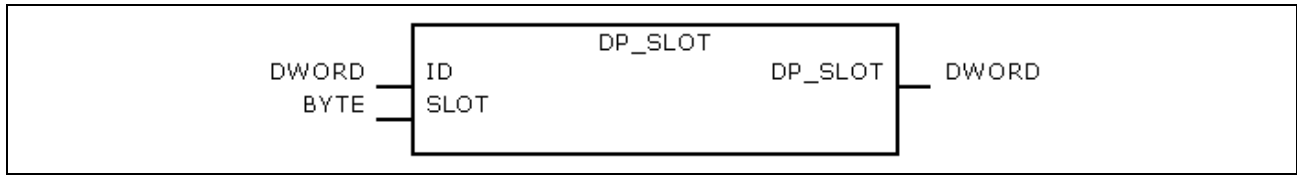
Fig. 6-59:   DP_SLOT

	Name	**Type**	**Comment**
VAR_INPUT	ID	DWORD	Slot handle
	SLOT	BYTE	Slot number
Function value		DWORD	Slot handle

Fig. 6-60:   Interface of DP_SLOT

6.6   RIL_Utilities

Overview

| Designation	Type	Description
Version_RIL_Utilities_01V*	FNC	Function Version_RIL_Utilities_01V* serves for the version management of library RIL_Utilities.lib.
IL_HighResTimeTick	FNC	Function IL_HighResTimeTick reads the high resolution time tick of the system.
IL_HighResTimeDiff	FNC	Function IL_HighResTimeDiff calculates the time difference of two high resolution time ticks of the system in microseconds.
IL_Date	FNC	Function IL_Date reads the current system date.
IL_TimeOfDay	FNC	Function IL_TimeOfDay reads the current system time.
IL_DateAndTime	FNC	Function IL_DateAndTime reads the current system date and time.
IL_SysTime64	FB	Function block IL_SysTime64 reads the current system date and time.
IL_SysTimeDate	FB	Function block IL_SysTimeDate reads the current system date and time.
IL_ExtSysTimeDate	FB	Function block IL_ExtSysTimeDate reads the current system date and time.
IL_SysTime64ToSysTimeDate	FB	Function block IL_SysTime64ToSysTimeDate converts the format of the system date and time.
IL_SysTimeDateToSysTime64	FB	Function block IL_SysTimeDateToSysTime64 converts the format of the system date and time.

Fig. 6-61: Overview of the function blocks and functions contained in library
RIL_Utilities.lib

Designation	Type	Description
n/a	n/a	n/a

Fig. 6-62: Overview of the data types contained in library RIL_Utilities.lib

Designation	Type	Description
n/a	n/a	n/a

Fig. 6-63: Overview of the global variables contained in library RIL_Utilities.lib

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Data Types

Library RIL_Utilities.lib does not contain any separate data types.

Global Variables

Library RIL_Utilities.lib does not contain any separate global variables.

Version_RIL_Utilities_01V*

Function Version_RIL_Utilities_01V*[1] serves for version management of library RIL_Utilities.lib.
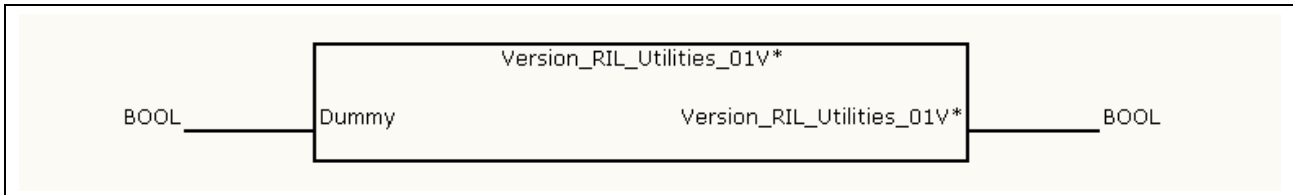
Fig. 6-64:   Interface of: Version_RIL_Utilities_01V*

	Name	Type	Comment
VAR_INPUT	Dummy	BOOL	Dummy
Function value	Version_RIL_Utilities_01V*	BOOL	Acknowledgment that the library is valid

Fig. 6-65: Interface of version_RIL_Utilities_01V*

Specification   Function Version_RIL_Utilities_01V* restricts the use of library RIL_Utilities.lib to the valid system as well as to a certain number of valid releases.

Function Version_RIL_Utilities_01V* also shows the user the current release status of library RIL_Utilities.lib and contains an overview of all previously made modifications.

Note: Library RIL_Utilities.lib is available on several platforms (systems) in the programming system "IndraLogic; its functional range is adapted to the respective system.

Functional Description   If library RIL_Utilities.lib is integrated in a project, function Version_RIL_Utilities_01V* restricts the download of the whole project to the valid system as well as to a valid release. If a system or a release is invalid, the corresponding system function is not available and, thus, cannot be addressed (Fig. 6-66).

Note: The verification of the system and the releases is also active, if function Version_RIL_Utilities_01V* is not used.

---

[1] (*) Release

Check_Version_RIL_Utilities_01Vs.bmp
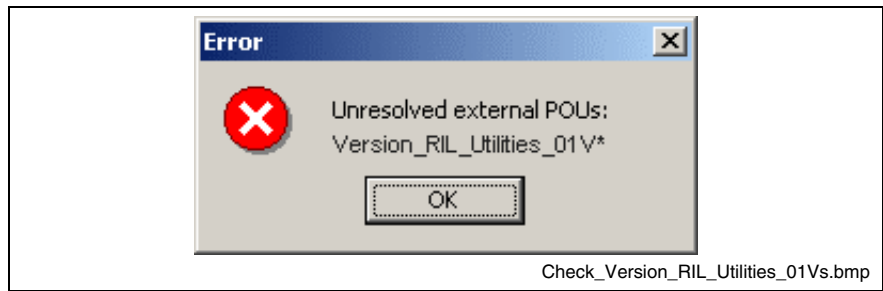
Fig. 6-66:   Message: version check of the system failed

| **Note:** | Generally, besides the version function also further functions are indicated as not existing and, thus, cannot be integrated in the project. |

If function Version_RIL_Utilities_01V* is error-free addressed, it signals permanently TRUE as return value.

| **Note:** | Function Version_RIL_Utilities_01V* has no functional meaning for parts of the library and must not be used in the project. |

IL_HighResTimeTick

Function IL_HighResTimeTick reads the high resolution time tick of the system.
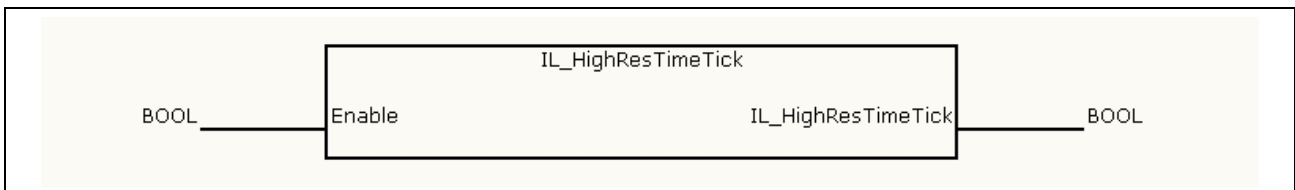
Fig. 6-67:   IL_HighResTimeTick

	Name	**Type**	**Comment**
VAR_INPUT	Enable	BOOL	Processing enable of the function (cyclic, status-controlled)
Function value	IL_HighResTimeTick	UDINT	High resolution time tick of the system

Fig. 6-68: Interface of IL_HighResTimeTick

Specification   Function IL_HighResTimeTick in combination with function IL_HighResTimeDiff is used to determine the runtime of a code segment (Fig. 6-69).

| **Note:** | The return value of function IL_HighResTimeTick should not be used as time value due to the special system-specific time basis. |

Functional Description   After the processing enable with "Enable" function IL_HighResTimeTick retrieves cyclically the high resolution time tick of the system.
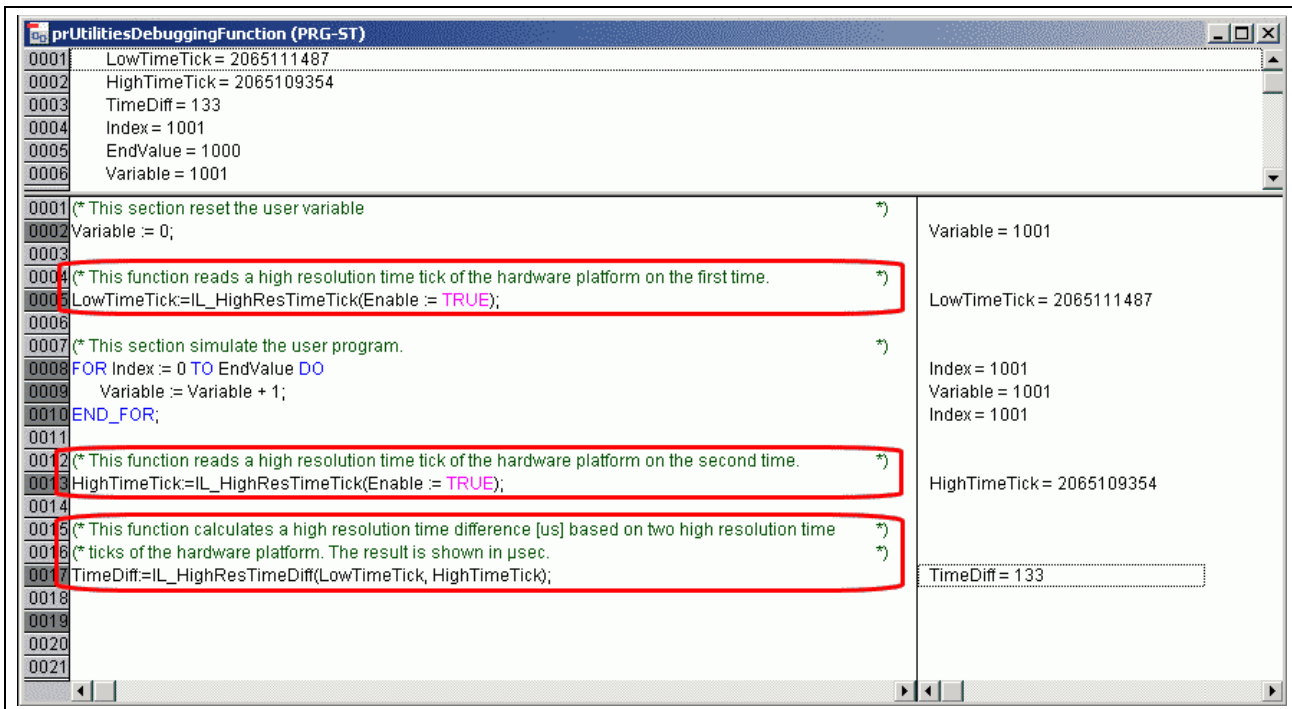
Fig. 6-69:   Application example of function IL_HighResTimeTick

IL_HighResTimeDiff

Function IL_HighResTimeDiff calculates the time difference of two high resolution time ticks of the system in microseconds.
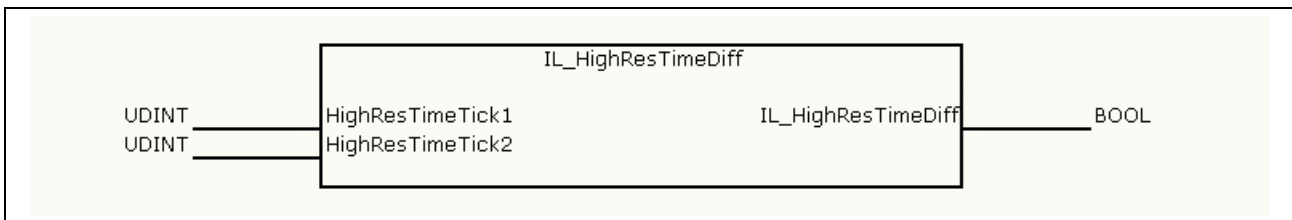
Fig. 6-70:   IL_HighResTimeDiff

	Name	Type	Comment
VAR_INPUT	Enable	BOOL	Processing enable of the function (cyclic, status-controlled)
	HighResTimeTick1	UDINT	High resolution time tick of the system before the code segment
	HighResTimeTick2	UDINT	High resolution time tick of the system after the code segment
Function value	IL_HighResTimeDiff	UDINT	Time difference of two high resolution time ticks of the system in [us]

Fig. 6-71: Interface of IL_HighResTimeDiff

Specification   Function   IL_HighResTimeDiff   in   combination   with   function IL_HighResTimeTick is used to determine the runtime of code segment (Fig. 6-69).

Note:	Reading out the high resolution time tick requires approx. one to two microseconds depending on the system. If necessary, the user can add this time, when he determines the time difference.

Functional Description

After the processing enable with "Enable" function IL_HighResTimeDiff calculates cyclically the time difference of two high resolution time ticks of the system in microseconds.

IL_Date

Function IL_Date reads the current system date.
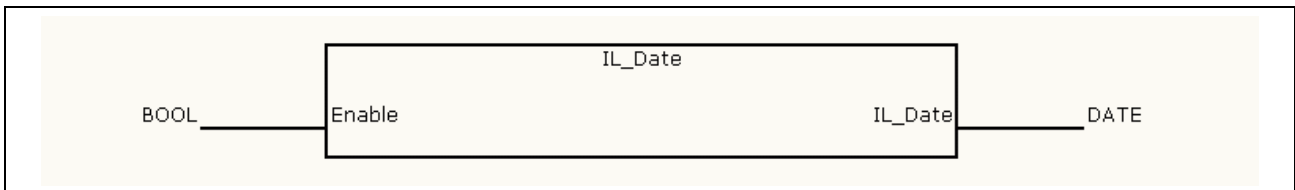
Fig. 6-72:   IL_Date

	Name	Type	Comment
VAR_INPUT	Enable	BOOL	Processing enable of the function (cyclic, status-controlled)
RETURN	IL_Date	DATE	Current system date according to IEC61131-3

Fig. 6-73: Interface of IL_Date

Functional Description

After the processing enable with "Enable" function IL_Date retrieves cyclically the system date formatted according to IEC61131-3.

IL_TimeOfDay

Function IL_TimeOfDay reads the current system time.
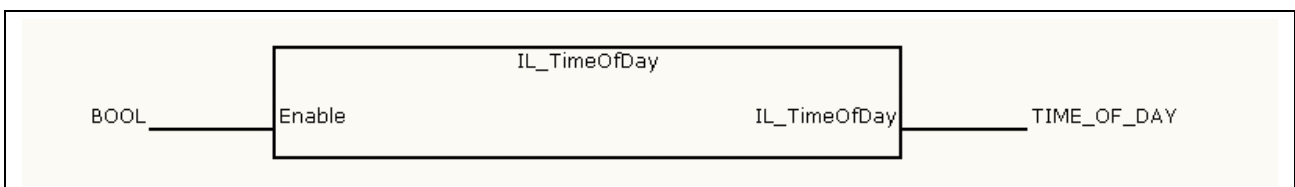
Fig. 6-74:   IL_TimeOfDay

	Name	Type	Comment
VAR_INPUT	Enable	BOOL	Processing enable of the function (cyclic, status-controlled)
RETURN	IL_TimeOfDay	TOD	Current system time according to IEC61131-3

Fig. 6-75: Interface of IL_TimeOfDay

Functional Description

After the processing enable with "Enable" function IL_TimeOfDay retrieves cyclically the system time formatted according to IEC61131-3.

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IL_DateAndTime

Function IL_DateAndTime reads the current system date and time.
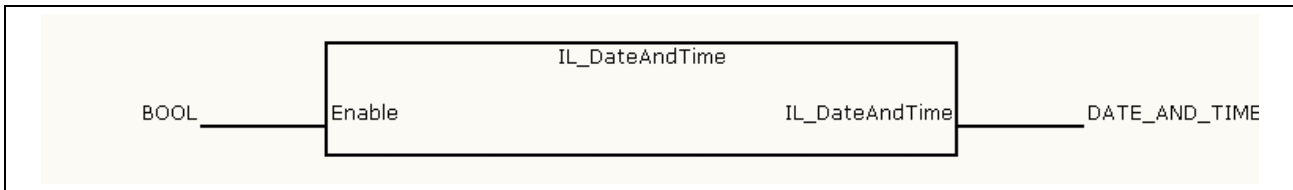
Fig. 6-76:   IL_DateAndTime

	Name	Type	Comment
VAR_INPUT	Enable	BOOL	Processing enable of the function (cyclic, status-controlled)
RETURN	IL_DateAndTime	DT	Current system date and time according to IEC61131-3

Fig. 6-77: Interface of IL_DateAndTime

Functional Description   After the processing enable with "Enable" function IL_DateAndTime retrieves cyclically the current system date as well as the current system time in formatted manner according to IEC61131-3.

IL_SysTime64

Function block IL_SysTime64 reads the current system date and time.
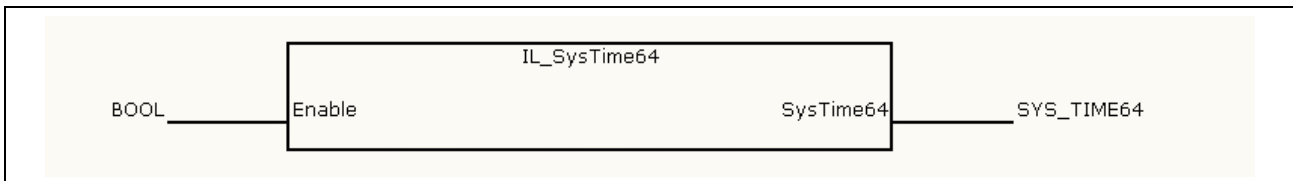
Fig. 6-78:   IL_SysTime64

	Name	Type	Comment
VAR_INPUT	Enable	BOOL	Processing enable of the function block (cyclic, status-controlled)
VAR_OUTPUT	SysTime64	SYS_TIME64	Current system date and time in microseconds since 1970-01-01

Fig. 6-79: Interface of IL_SysTime64

Functional Description   After the processing enable with "Enable" function block IL_SysTime64 retrieves cyclically the current system date and time in microseconds since 1970-01-01.

IL_SysTimeDate

Function block IL_SysTimeDate reads the current system date and time.
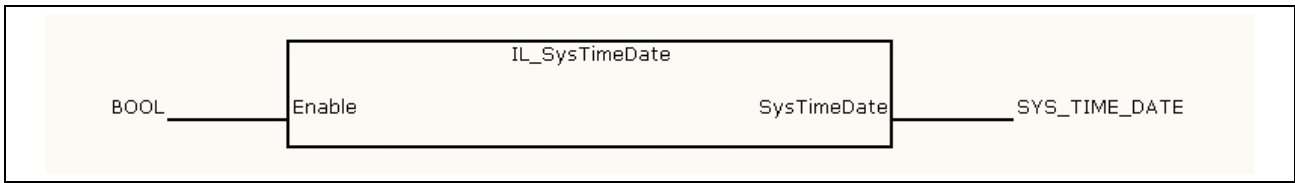
Fig. 6-80:   IL_SysTimeDate

	Name	**Type**	**Comment**
VAR_INPUT	Enable	BOOL	Processing enable of the function block (cyclic, status-controlled)
VAR_OUTPUT	SysTimeDate	SYS_TIME_DATE	Current system date and time in system format

Fig. 6-81: Interface variables – function block: IL_SysTimeDate

Functional Description After the processing enable with "Enable" function block IL_SysTimeDate retrieves cyclically the current system date and time in system format.

IL_ExtSysTimeDate

Function block IL_ExtSysTimeDate reads the current system date and time.
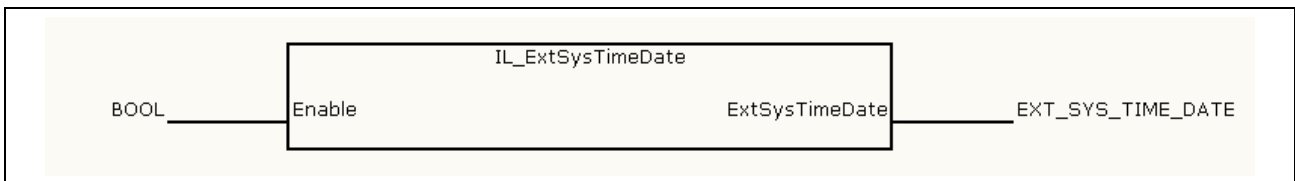
Fig. 6-82:   IL_ExtSysTimeDate

	Name	**Type**	**Comment**
VAR_INPUT	Enable	BOOL	Processing enable of the function block (cyclic, status-controlled)
VAR_OUTPUT	ExtSysTimeDate	EXT_SYS_ TIME_DATE	Current system date and time in extended system format

Fig. 6-83: Interface variables – function block: IL_ExtSysTimeDate

Functional Description After the processing enable with "Enable" function block IL_ExtSysTimeDate retrieves cyclically the current system date and time in extended system format.

Note: The extended system format consists of the system formats SYS_TIME64 as well as SYS_TIME_DATE.

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IL_SysTime64ToSysTimeDate

Function block IL_SysTime64ToSysTimeDate converts the format of the system date and time.
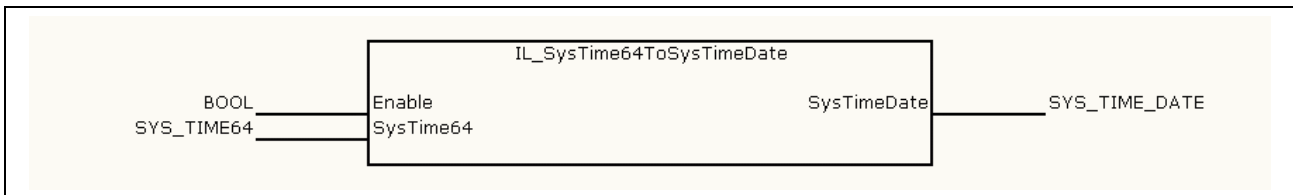
Fig. 6-84:   IL_SysTime64ToSysTimeDate

	Name	Type	Comment
VAR_INPUT	Enable	BOOL	Processing enable of the function block (cyclic, status-controlled)
	SysTime64	SYS_TIME64	System date and time in microseconds since 1970-01-01
VAR_OUTPUT	SysTimeDate	SYS_TIME_DATE	System date and time in system format

Fig. 6-85: Interface variables – function block: IL_SysTime64ToSysTimeDate

Functional Description After the processing enable with "Enable" function block IL_SysTime64ToSysTimeDate converts cyclically the system date including system time in microseconds applied at input "SysTime64" (basis: 1970-01-01) into the system date and time in system format.

IL_SysTimeDateToSysTime64

Brief Description Function block IL_SysTimeDateToSysTime64 converts the format of the system date and time.
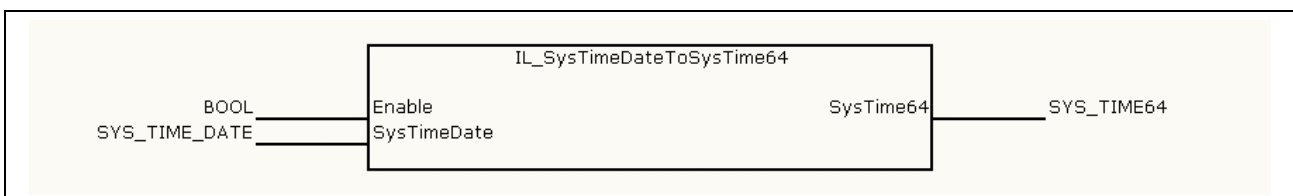
Fig. 6-86:   IL_SysTimeDateToSysTime64

	Name	Type	Comment
VAR_INPUT	Enable	BOOL	Processing enable of the function block (cyclic, status-controlled)
	SysTimeDate	SYS_TIME_DATE	System date and time in system format
VAR_OUTPUT	SysTime64	SYS_TIME64	System date and time in microseconds since 1970-01-01

Fig. 6-87: Interface variables – function block: IL_SysTimeDateToSysTime64

Functional Description After the processing enable with "Enable" function block IL_SysTimeDateToSysTime64 converts cyclically the system date including system time in microseconds applied at input "SysTimeDate" (basis: 01st January 1970).

6.7 SysLibDPV1Hilscher

When using this library, the DPV1 services of the Hilscher DP master (DP master class 1) are provided.

Note: We recommend to use the more comprehensive library RIL_ProfibusDP.lib instead of the BusDiag.lib.

You will find further information on the SysLibDPV1Hilscher.lib in the description of the Hilscher bus card.

Notes

7   SoftPanel – Operating and Displaying

7.1   Overview

The operating and display program SoftPanel constitutes within the IndraLogic VPP 21 the link between Windows and the Software PLC "SoftControl" with its real time operating system VxWorks.

At first, an executable PLC program is created and loaded with IndraLogic. The I/O data of the PLC are exchanged via the integrated field bus. Thus, the configuration of inputs and outputs within IndraWorks is required. To commission the Software PLC, on the one hand IndraLogic and on the other hand the SoftPanel program might be used.
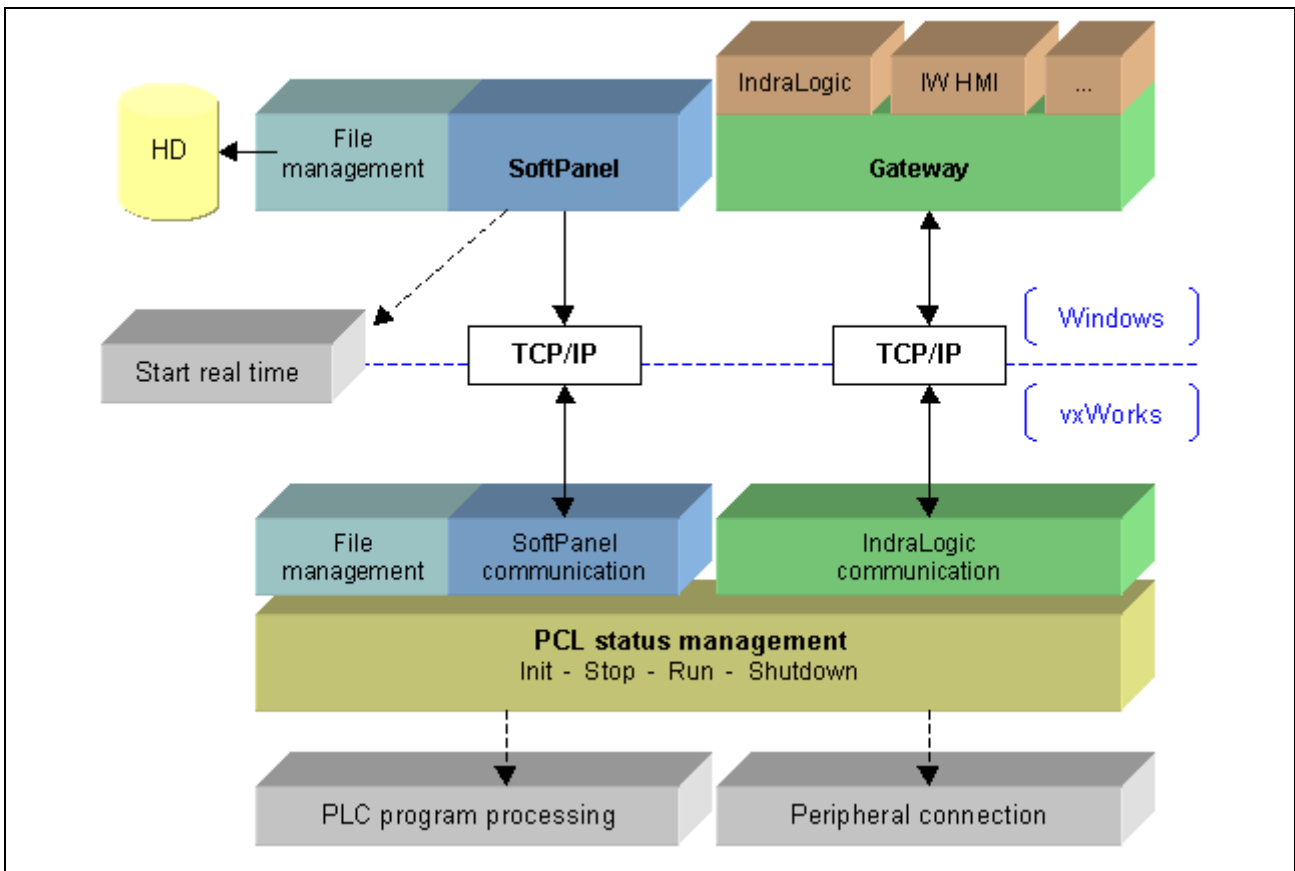
Fig. 7-1:   Principle of the internal communication between Windows and the real time operating system VxWorks

The following section illustrates the system requirements and the use of the single components. In addition, the most important differences compared with a conventional Hardware PLC are described.

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7.2   Installation

Requirements

Condition of Delivery When the IndraLogic VPP 21 is delivered, SoftControl, SoftPanel and the necessary real time components VxWorks are already installed and directly usable. However, during the remote programming the installation of the mentioned components might be necessary. In this case please consider the installation instructions mentioned below.

System Requirements Generally, the system requirements are already checked during the installation of SoftPanel. If these requirements are not fulfilled, a message appears:

- Required hard disk space before the installation of SoftPanel: At least 40 Mbytes

- Recommended RAM memory: at least 256 Mbytes

- Operating system Windows 2000 (as of Service Pack 3) or Windows XP (as of Service Pack 1)

Installation Process The installation is divided into three operating steps:

- Installing the driver

- Calculating the memory requirements and entering the value into the "Boot.ini"

- Shutting-down and restarting Windows

Installing the Driver

Call up batch file **VPP 21DevInst.bat**. With the batch file all drivers required for the operation of the SoftControl are installed. The batch file is located in subdirectory "\SoftControl\Data" of the IndraWorks installation.

Example C:\Program Files\Rexroth\IndraWorks\SoftControl\Data\ VPP 21DevInst.bat

Calculating and Entering the Memory Requirements

To determine the current memory requirements, please call up the system properties:

My computer → Properties

– or –

Start → Settings → Control Panel → System

System Properties The "General" tab shows the available total memory, see red mark in the following figure.
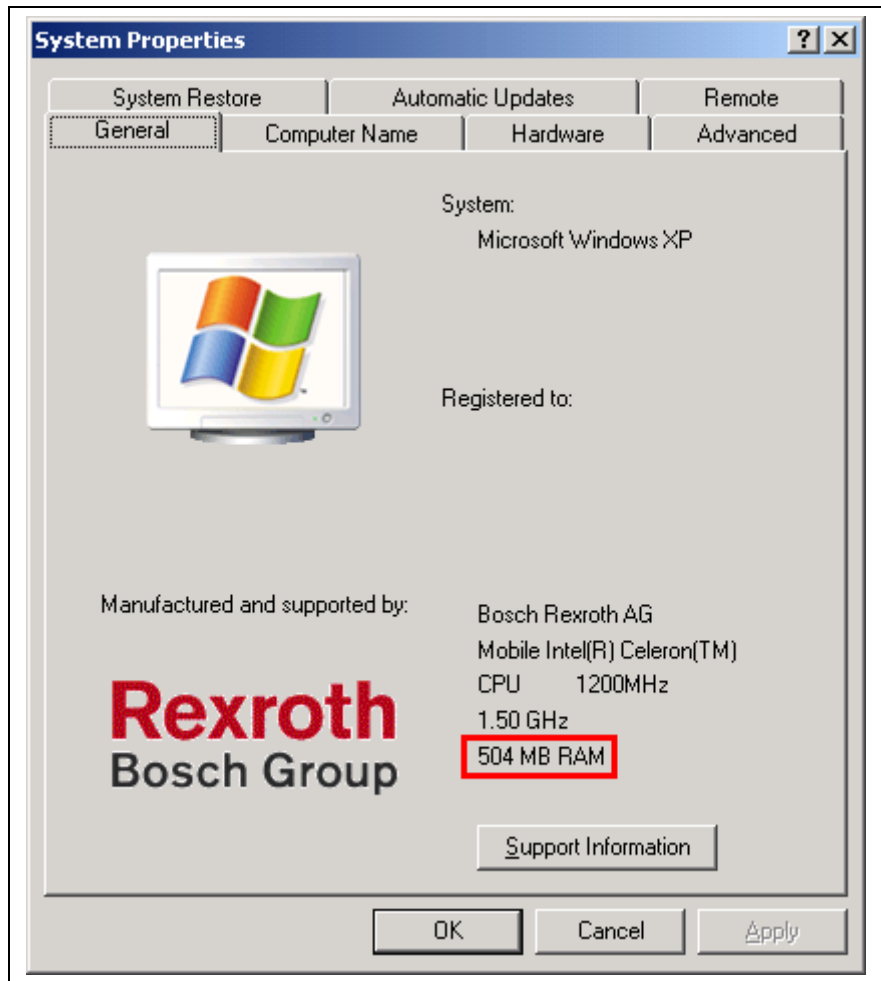
Fig. 7-2:   System properties

Subtract the memory of 48 MB required for the SoftControl from the available total memory.

Available total memory	504 MB
PLC memory	-48 MB
Result (for "/maxmem")	= 456 MB

Fig. 7-3:   Example for the memory calculation

Adapt "Boot.ini"   The result is entered as parameter "/maxmem=" in file "Boot.ini", see yellow mark in the following figure. This file is located in the root directory, e. g. "C:\". This file can be selected in the Windows explorer and can be opened for editing with the right mouse button.

Note: The file is only visible, if a special setting of the Windows explorer is made (e. g. "Display protected system files"). The possibly existing write protection must be reset.

Observe that you assign under [operating systems] the parameter to the active operating system, if several operating systems are available. It is entered behind the keyword "default" under [boot loader], see red mark in the following figure.

Save the "Boot.ini" file and close the editor.

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```
[boot loader]
default=multi(0)disk(0)rdisk(0)partition(1)\WINDOWS
timeout=2
[operating systems]
multi(0)disk(0)rdisk(0)partition(1)\WINDOWS="Microsoft windows XP Professional" /fastdetect /maxmem=456
```

Fig. 7-4:   Example of the re-calculated "maxmen" value in the "Boot.ini" file

Restart System

Windows must be shut-down and restart to apply the optimized system parameters. The Installation is now completed.

7.3   Interaction with Other Components

The following listing shows, which Windows programs and hardware can generally be used without any problems in combination with the SoftControl:

- Serial and parallel interfaces to use modems, printers, etc.

- Services and programs used to organize files, e. g. Explorer, ScanDisc, defragmentation (but only systematically and not via the automatic system service)

- Office applications, as e. g. text processing, graphic programs, CAD, auxiliary programs

- Computer virus protection software, but no automatic virus monitoring in the background

Please only use as many additional hardware components and start as less programs simultaneously as necessary.

Note: Due to the real time requirement of the SoftControl, it might occur, that Windows reacts delayed. You can e. g. recognize this, if a movement of the mouse is not floating, but jerkily. This behavior represents no disturbance or malfunction!

7.4   Real Time Aspects

The integrated real time solution of the SoftControl provides for a safe solution concerning the real time capabilities, in spite of the insufficiencies of Windows 2000/XP. Windows has not any effect on the real time capabilities of the SoftControl.

7.5   Important Differences to the Hardware PLC

Operating Elements

Contrary to a Hardware PLC (e. g. IndraLogic L40) a SoftControl has no operating elements, e. g. status indicator and mains switch. SoftPanel replaces this missing operating elements.

Starting Behavior and PLC Shut Down

To call up SoftPanel corresponds to switching on the mains switch (Power-ON) of a conventional PLC.

If the SoftControl shall be put out of operation, the PLC must be "shut down". If you finish SoftPanel or Windows, the PLC is shut down. During the shut down important operating data are transmitted to the hard disk. These data are reloaded into the SoftControl during its next start-up.

If the SoftControl is shut down, the operating mode of the PLC is saved, so that this status is restored with the next start. Example: Before the shut down, the soft SoftControl was in the stop mode. If SoftPanel is recalled, the stop mode will be active again.

Remanence

Concerning a conventional PLC all data in the memory are generally remanent, if a voltage breakdown occurred. As a PC can't recognize a voltage breakdown, the remanence of the SoftControl is only available by a systematic "shut down". The remanence behavior is system- or device-specifically set (see below).

When starting the SoftControl, the remanent data are transmitted from the hard disk of the PC to the memory of the SoftControl. The transmitted data are the data of the current project. When closing (shut down) the SoftControl, the current data are transmitted from the memory of the SoftControl back to the hard disk. This process is managed by the SoftPanel program.

System Crashes

So-called crashes of the operating system can never be entirely excluded. As the SoftControl has its own real time operating system, it keeps running after a crash.

- In this case SoftPanel could be inoperable. Thus, the PLC can't be shut down anymore.

- All resources are managed by Windows. Hence, you have no longer access to e.g. the hard disc to save the remanent data.

- The communication between SoftPanel and SoftControl is interrupted.

More Safety

To avoid the consequences of a voltage breakdown, it is possible to use an uninterruptible power supply (UPS). The UPS indicates Windows, that a voltage breakdown has occurred. Thus, an automatic "Shut down" of the installation without any data losses is initiated.

The operator terminal IndraControl VPP 21 represents a powerful industrial PC with integrated UPS.

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7.6   Parameterization While Calling Up SoftPanel

It is possible to configure the SoftPanel software individually via function switches (call parameters). This switches can be registered in the start file **SOFTPANEL.INI** before calling it. This file must be located in the directory of SoftPanel.

One parameter can be specified in each line of the start file. The parameter must be directly set at the beginning of a line. Comments can be introduced by a semicolon.

Example:

```
; File: SOFTPANEL.INI
/C192.0.1.10        ; Use ClientIP address
/M                  ; Don't output messages
```

The current function switches can be reached in SoftPanel via menu function „Help, Parameter".

The following SoftPanel function switches are possible:

Function switch	Effect
/Cnnn.nnn.nnn.nnn	Specify client IP address (optional) e. g.: /C192.0.1.2 If this parameter is omitted, SoftPanel retrieves this information from the VxWin.ini file.
/M	Don't output messages, don't open dialog windows, don't request user inputs. Important for remanent operation: Finish SoftPanel immediately without request and save all data.
/Snnn.nnn.nnn.nnn	Specify server IP address (optional) e. g.: /S192.0.1.1 If this parameter is omitted, SoftPanel retrieves this information from the VxWin.ini file.
/Vnnnn	Start of the real time operating system VxWorks with memory reservation. nnnn indicates the memory reserved under Windows in kbytes. Example: /V8192: For the SoftControl approx. 8 Mbytes are reserved. If a value less than 8192 is indicated, it is internally operated with value 8192. A greater value increases the reserved memory space.
/Ynn	This switch controls the various functions of the SoftControl. The functions are bit-coded and can be combined with each other as required. The total of the bit ratings is transmitted as parameter in decimal (nn) manner: Bit rating Meaning 1 Deactivate IndraLogic communication 64 Trace information active (console) Examples: /Y1 -> IndraLogic communication is deactivated. /Y65 -> Trace information is output to the Telnetport (Y64) and IndraLogic communication is deactivated (Y1).

Fig. 7-5:   SoftPanel function switch (call parameters)

Note: The following function switch is not provided for the "normal" operation of the SoftControl. Please use this switch only after consulting the Bosch Rexroth Support.

Function switch	Effect
/D	All write/read accesses to the hard disk are recorded and archived in the protocol files FileIO.txt or FileIO1.txt (SoftPanel directory). **This parameter may only be set to support the error search after consulting the Bosch Rexroth Support, as it charges the system resources during normal operation.**

Fig. 7-6:   Support function switch

7.7   Screen Layout

SoftPanel contains operating and display elements. Operating elements are grouped in the menu and symbol bar. The display area split into two windows (PLC and periphery) and the status bar serve as display elements.
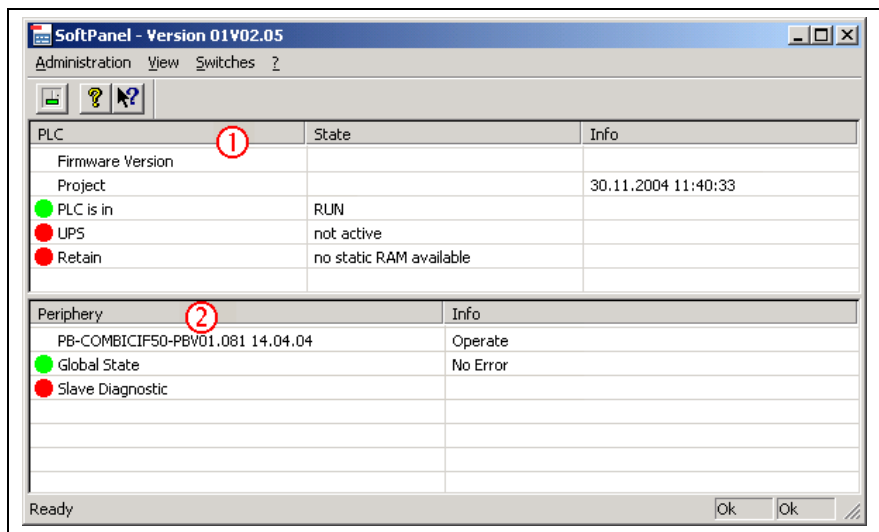
(1)   PLC
(2)   Periphery
Fig. 7-7:   SoftPanel: screen layout

PLC (1)   The display of the PLC (SoftControl) shows the states and their causes. Here, the error messages are indicated in plain text.

Periphery (2)   In this window information and error messages of the internal field bus and the connected peripheral equipment are listed.

7.8   System Parameters

Select menu function "Administration, Change system parameters", to change the system behavior.

⚠️ **CAUTION**

Modifications of the system parameters can cause unpredictable behavior of the SoftControl or the Windows operating system!

⇒   The system parameters may only be modified by instructed specialists and only after prior agreement with the Bosch Rexroth Support!

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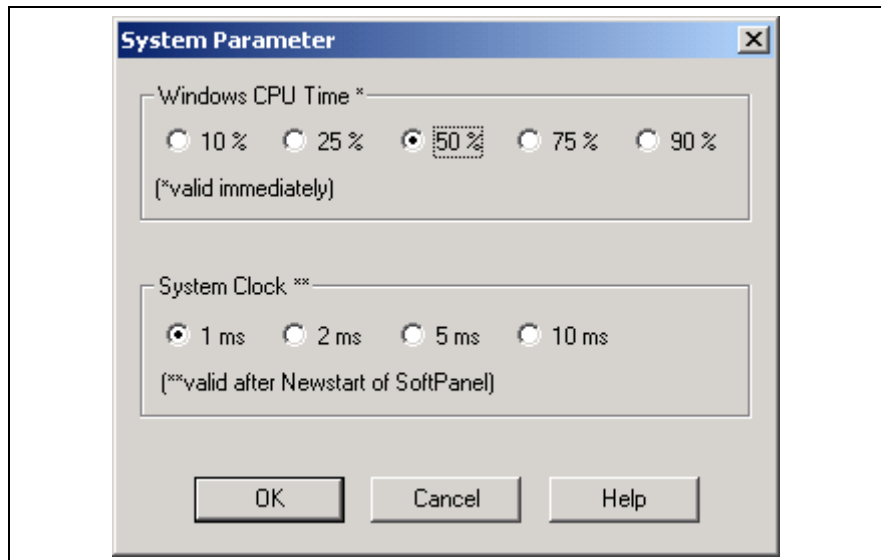
Fig. 7-8:   System parameters

Windows Computing Time   This parameter determines the relation of the assigned computing time between the real time operating system and Windows. The smaller the value, the less computing time is assigned to Windows. The default value is 50%.

Note: Due to the real time requirement of the SoftControl, it might occur, that Windows reacts delayed. You can e. g. recognize this, if a movement of the mouse is not floating, but jerkily. This behavior represents no disturbance or malfunction!

System Clocks per Second   This value determines the frequency of accesses on the SoftControl. The set value influences the cycle time of the SoftControl. Example: 500 clocks/s correspond to a cycle time of 2 milliseconds. The default setting is 1000 clocks/s (1 ms cycle time).

A modification of the system clock is only activated after a restart of SoftPanel.

7.9   Switch PLC to Run/Stop

By using menu function "Switches, Switch PLC to Run/Stop" you can change the SoftControl – according to the current status – from Run to Stop, or from Stop to Run.

Note: The switch status must not correspond to the current status of the PLC. Thus, the SoftControl can remain in the STOP status, e. g. caused by an error in the application program, although the switch was set to "Run".

The switch position is indicated with the Run/Stop button in the symbol bar (see figure below) and the current status of the PLC in the SoftPanel display box.
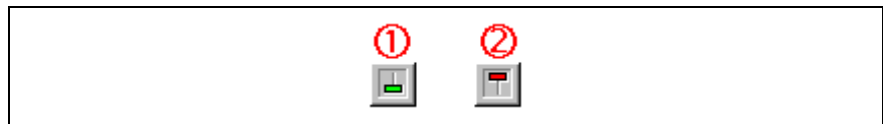
(1)   Switch is on "Run"
(2)   Switch is on "Stop"

Fig. 7-9:   Switch, Switch PLC to Run/Stop

If the SoftControl is shut down (exit SoftPanel), also the switch position of the SoftControl is saved, so that this status is restored with the next start. Example: Before the shut down, the SoftControl was in the stop mode. When SoftPanel is recalled, the stop mode of the SoftControl will be active again.

7.10 Shutting Down the PLC – Exit SoftPanel

By using menu function "Administration, Exit" SoftPanel and the SoftControl are put out of operation.

After that, the SoftControl is "shut down". Also if you finish Windows, the SoftControl is automatically shut down. During the shut down important operating data are transmitted to the hard disk. These data are reloaded into the SoftControl during its next start-up.

If the SoftControl is shut down, the operating mode of the PLC is saved, so that this status is restored with the next start. Example: Before the shut down, the SoftControl was in the stop mode. When SoftPanel is recalled, the stop mode will be active again.

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Notes

8   Technical Data

8.1   Equipment

IndraLogic VPP 21-01VRS	
Processor	Pentium III with 700 MHz
Main memory	504 MB minus 48 MB for the SoftControl (456 MB)

Interfaces:
        Communication
        interfaces
	2 x Ethernet connections (RJ 45, 10/100 Base-T)
	1 x Profibus DP master interface

Fig. 8-1:   Equipment

8.2   Power Data

IndraLogic VPP 21-01VRS	
User memory for program code	8 Mbytes
User memory for data	16 Mbytes
Remanent memory	2 Mbytes
Task number	32
Processing time, typical (1000 instructions in IL, bit and word commands mixed)	50 µs
Profibus DP master according to IEC 61158-3	

Fig. 8-2:   Power data

Notes

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11   Service & Support

11.1 Helpdesk

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Our service helpdesk at our headquarters in Lohr am Main, Germany can assist you in all kinds of inquiries. Contact us

- telefonisch - by phone:
über Service Call Entry Center
- via Service Call Entry Center

+49 (0) 9352 40 50 60
Mo-Fr 07:00-18:00
Mo-Fr 7:00 am - 6:00 pm

- per Fax - by fax:

+49 (0) 9352 40 49 41

- per e-Mail - by e-mail: **service.svc@boschrexroth.de**

11.2 Service-Hotline

Außerhalb der Helpdesk-Zeiten ist der Service direkt ansprechbar unter

After helpdesk hours, contact our service department directly at

+49 (0) 171 333 88 26

oder - or   **+49 (0) 172 660 04 06**

11.3 Internet

Unter **www.boschrexroth.com** finden Sie ergänzende Hinweise zu Service, Reparatur und Training sowie die **aktuellen** Adressen *) unserer auf den folgenden Seiten aufgeführten Vertriebs- und Servicebüros.

At **www.boschrexroth.com** you may find additional notes about service, repairs and training in the Internet, as well as the **actual** addresses *) of our sales- and service facilities figuring on the following pages.

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Außerhalb Deutschlands nehmen Sie bitte zuerst Kontakt mit unserem für Sie nächstgelegenen Ansprechpartner auf.

	sales agencies
	offices providing service

Please contact our sales / service office in your area first.

*) Die Angaben in der vorliegenden Dokumentation können seit Drucklegung überholt sein.

*) Data in the present documentation may have become obsolete since printing.

11.4 Vor der Kontaktaufnahme... - Before contacting us...

Wir können Ihnen schnell und effizient helfen wenn Sie folgende Informationen bereithalten:

1. detaillierte Beschreibung der Störung und der Umstände.

2. Angaben auf dem Typenschild der betreffenden Produkte, insbesondere Typenschlüssel und Seriennummern.

3. Tel.-/Faxnummern und e-Mail-Adresse, unter denen Sie für Rückfragen zu erreichen sind.

For quick and efficient help, please have the following information ready:

1. Detailed description of the failure and circumstances.

2. Information on the type plate of the affected products, especially type codes and serial numbers.

3. Your phone/fax numbers and e-mail address, so we can contact you in case of questions.

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11.5 Kundenbetreuungsstellen - Sales & Service Facilities

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Bosch Rexroth Sp.zo.o.
Biuro Poznan
ul. Dabrowskiego 81/85
60-529 Poznan
Tel.:   +48 061 847 64 62 /-63
Fax: +48 061 847 64 02
	East Electric S.R.L.
	Bdul Basarabia no.250, sector 3
	73429 Bucuresti
	Tel./Fax:: +40 (0)21 255 35 07
	     +40 (0)21 255 77 13
	Fax: +40 (0)21 725 61 21
	eastel@rdsnet.ro
		Bosch Rexroth Sp.zo.o.
		Str. Drobety nr. 4-10, app. 14
		70258 Bucuresti, Sector 2
		Tel.: +40 (0)1 210 48 25
		     +40 (0)1 210 29 50
		Fax: +40 (0)1 210 29 52
			Bosch Rexroth OOO
			Wjatskaja ul. 27/15
			127015 Moskau
			Tel.: +7-095-785 74 78
			     +7-095 785 74 79
			Fax: +7 095 785 74 77
			laura.kanina@boschrexroth.ru

Russia Belarus - Weissrussland	Turkey - Türkei	Turkey - Türkei	Slowenia - Slowenien
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China	China	China	China
Bosch Rexroth China Ltd. 15/F China World Trade Center 1, Jianguomenwai Avenue Beijing 100004, P.R.China Tel.: +86 10 65 05 03 80 Fax: +86 10 65 05 03 79	Bosch Rexroth China Ltd. Guangzhou Repres. Office Room 1014-1016, Metro Plaza, Tian He District, 183 Tian He Bei Rd Guangzhou 510075, P.R.China Tel.: +86 20 8755-0030 +86 20 8755-0011 Fax: +86 20 8755-2387 stewart.cai_gz@boschrexroth.com.cn	Bosch Rexroth (China) Ltd. A-5F., 123 Lian Shan Street Sha He Kou District Dalian 116 023, P.R.China Tel.: +86 411 46 78 930 Fax: +86 411 46 78 932	Melchers GmbH BRC-SE, Tightening & Press-fit 13 Floor Est Ocean Centre No.588 Yanan Rd. East 65 Yanan Rd. West Shanghai 200001 Tel.: +86 21 6352 8848 Fax: +86 21 6351 3138
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Bosch Rexroth (China) Ltd. 6th Floor, Yeung Yiu Chung No.6 Ind Bldg. 19 Cheung Shun Street Cheung Sha Wan, Kowloon, Hongkong
Tel.:   +852 22 62 51 00
Fax: +852 27 41 33 44
alexis.siu@boschrexroth.com.hk
	Bosch Rexroth (India) Ltd. Electric Drives & Controls Plot. No.96, Phase III Peenya Industrial Area Bangalore – 560058
	
	Tel.: +91 80 51 17 0-211...-218
	Fax: +91 80 83 94 345
	          +91 80 83 97 374
	mohanvelu.t@boschrexroth.co.in
		Bosch Rexroth (India) Ltd. Electric Drives & Controls Advance House, II Floor Ark Industrial Compound Narol Naka, Makwana Road Andheri (East), Mumbai - 400 059
		
		Tel.: +91 22 28 56 32 90
		          +91 22 28 56 33 18
		Fax: +91 22 28 56 32 93
		singh.op@boschrexroth.co.in
			Bosch Rexroth (India) Ltd. S-10, Green Park Extension New Delhi – 110016
			
			Tel.: +91 11 26 56 65 25
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Fax: +62 21 7891170 - 71
rudy.karimun@boschrexroth.co.id
	Bosch Rexroth Automation Corp. Service Center Japan Yutakagaoka 1810, Meito-ku, NAGOYA 465-0035, Japan
	
	Tel.: +81 52 777 88 41
	          +81 52 777 88 53
	          +81 52 777 88 79
	Fax: +81 52 777 89 01
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			Fax: +82 222 641 295

Korea	Korea	Malaysia	Singapore - Singapur
Bosch Rexroth-Korea Ltd. Electric Drives & Controls 1515-14 Dadae-Dong, Saha-gu Pusan Metropolitan City, 604-050 Tel.: +82 51 26 00 741 Fax: +82 51 26 00 747 eunkyong.kim@boschrexroth.co.kr	Bosch Rexroth-Korea Ltd. Electric Drives & Controls 1515-14 Dadae-Dong, Saha-gu Ulsan, 680-010 Tel.: +82 52 256-0734 Fax: +82 52 256-0738 keonhyun.jeong@boschrexroth.co.kr	Bosch Rexroth Sdn.Bhd. 11, Jalan U8/82, Seksyen U8 40150 Shah Alam Selangor, Malaysia Tel.: +60 3 78 44 80 00 Fax: +60 3 78 45 48 00 hhlim@boschrexroth.com.my rexroth1@tm.net.my	Bosch Rexroth Pte Ltd 15D Tuas Road Singapore 638520 Tel.: +65 68 61 87 33 Fax: +65 68 61 18 25 lai.ts@boschrexroth.com.sg
South Africa - Südafrika	Taiwan	Taiwan	Thailand
TECTRA Automation (Pty) Ltd. 100 Newton Road, Meadowdale Edenvale 1609 Tel.: +27 11 971 94 00 Fax: +27 11 971 94 40 **Hotline: +27 82 903 29 23** georgv@tectra.co.za	Bosch Rexroth Co., Ltd. Taichung Industrial Area No.19, 38 Road Taichung, Taiwan 407, R.O.C. Tel : +886 - 4 -235 08 383 Fax: +886 - 4 -235 08 586 jim.lin@boschrexroth.com.tw david.lai@boschrexroth.com.tw	Bosch Rexroth Co., Ltd. Tainan Branch No. 17, Alley 24, Lane 737 Chung Cheng N.Rd. Yungkang Tainan Hsien, Taiwan, R.O.C. Tel : +886 - 6 –253 6565 Fax: +886 - 6 –253 4754 charlie.chen@boschrexroth.com.tw	NC Advance Technology Co. Ltd. 59/76 Moo 9 Ramintra road 34 Tharang, Bangkhen, Bangkok 10230 Tel.: +66 2 943 70 62 +66 2 943 71 21 Fax: +66 2 509 23 62 Hotline +66 1 984 61 52 sonkawin@hotmail.com

Rexroth
Bosch Group

Nordamerika – North America

USA Headquarters - Hauptniederlassung	USA Central Region - Mitte	USA Southeast Region - Südost	USA SERVICE-HOTLINE
Bosch Rexroth Corporation Electric Drives & Controls 5150 Prairie Stone Parkway Hoffman Estates, IL 60192-3707 Tel.: +1 847 645-3600 Fax: +1 847 645-6201 servicebrc@boschrexroth-us.com repairbrc@boschrexroth-us.com	Bosch Rexroth Corporation Electric Drives & Controls 1701 Harmon Road Auburn Hills, MI 48326 Tel.: +1 248 393-3330 Fax: +1 248 393-2906	Bosch Rexroth Corporation Electric Drives & Controls 2810 Premiere Parkway, Suite 500 Duluth, GA 30097 Tel.: +1 678 957-4050 Fax: +1 678 417-6637	- 7 days x 24hrs - **+1-800-REXROTH** **+1 800 739-7684**
USA Northeast Region – Nordost	USA West Region – West		
Bosch Rexroth Corporation Electric Drives & Controls 99 Rainbow Road East Granby, CT 06026 Tel.: +1 860 844-8377 Fax: +1 860 844-8595	Bosch Rexroth Corporation Electric Drives & Controls 7901 Stoneridge Drive, Suite 220 Pleasanton, CA 94588 Tel.: +1 925 227-1084 Fax: +1 925 227-1081		
Canada East - Kanada Ost	Canada West - Kanada West	Mexico	Mexico

Bosch Rexroth Canada Corporation
Burlington Division
3426 Mainway Drive
Burlington, Ontario
Canada L7M 1A8
 	
Tel.:   +1 905 335 5511
Fax: +1 905 335 4184
 	
michael.moro@boschrexroth.ca
	Bosch Rexroth Canada Corporation
	5345 Goring St.
	Burnaby, British Columbia
	Canada V7J 1R1
	
	Tel. +1 604 205 5777
	Fax +1 604 205 6944
	
	david.gunby@boschrexroth.ca
		Bosch Rexroth Mexico S.A. de C.V.
		Calle Neptuno 72
		Unidad Ind. Vallejo
		07700 Mexico, D.F.
		
		Tel.: +52 55 57 54 17 11
		Fax: +52 55 57 54 50 73
		mario.francioli@boschrexroth.com.mx
			Bosch Rexroth S.A. de C.V.
			Calle Argentina No 3913
			Fracc. las Torres
			64930 Monterrey, N.L.
			
			Tel.: +52 81 83 65 22 53
			       +52 81 83 65 89 11
			       +52 81 83 49 80 91
			Fax: +52 81 83 65 52 80

Südamerika – South America

Argentina - Argentinien	Argentina - Argentinien	Brazil - Brasilien	Brazil - Brasilien

Bosch Rexroth S.A.I.C.
"The Drive & Control Company"
Rosario 2302
B1606DLD Carapachay
Provincia de Buenos Aires
 	
Tel.:   +54 11 4756 01 40
       +54 11 4756 02 40
       +54 11 4756 03 40
       +54 11 4756 04 40
Fax: +54 11 4756 01 36
       +54 11 4721 91 53
victor.jabif@boschrexroth.com.ar
	NAKASE SRL
	Servicio Tecnico CNC
	Calle 49, No. 5764/66
	B1653AOX Villa Balester
	Provincia de Buenos Aires
	
	Tel.: +54 11 4768 36 43
	Fax: +54 11 4768 24 13
	Hotline: +54 11 155 307 6781
	nakase@usa.net
	nakase@nakase.com
	gerencia@nakase.com (Service)
		Bosch Rexroth Ltda.
		Av. Tégula, 888
		Ponte Alta, Atibaia SP
		CEP 12942-440
		
		Tel.: +55 11 4414 56 92
		       +55 11 4414 56 84
		Fax sales: +55 11 4414 57 07
		Fax serv.: +55 11 4414 56 86
		alexandre.wittwer@rexroth.com.br
			Bosch Rexroth Ltda.
			R. Dr.Humberto Pinheiro Vieira, 100
			Distrito Industrial [Caixa Postal 1273]
			89220-390 Joinville - SC
			
			Tel./Fax: +55 47 473 58 33
			Mobil: +55 47 9974 6645
			
			sergio.prochnow@boschrexroth.com.br

Columbia - Kolumbien			
Reflutec de Colombia Ltda. Calle 37 No. 22-31 Santafé de Bogotá, D.C. Colombia Tel.: +57 1 368 82 67 +57 1 368 02 59 Fax: +57 1 268 97 37 reflutec@etb.net.co			